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Learning about perceived inflation target and stabilisation policy

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22th Augst 2006

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Objectives

- Analyse the interaction between:
 - private-sector uncertainty about inflation target
 (π*)
 - central-bank uncertainty about private-sector belief about π* (perceived inflation target)

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- Implications for
 - inflation persistence and volatility
 - time-varying inflation process

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Motivation 1: Uncertainty about perceived inflation target

Measures of perceived inflation target are noisy when monetary policy loses nominal anchor Example: US in late '70s-'80s

- Survey measures of LR inflation expectations as proxies
 - Blue chip survey: 8%
 - Michigan survey: 10-11%
- Model-based measures of belief about inflation target
 - Kozicki-Tinsley ('01, '05): 8 % (estimated target ~ 3.5%)
 - Bekaert et. al. ('05): 14%

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Survey measures of perceived inflation target

long run inflation expectations



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Model-based measures of perceived inflation target



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Motivation 2: inflation and misinformation

Orphanides-Williams '02 Percent 12 11 10 9 8 7 6 5 Forecast 4 Actual 3 2 1969 1971 1972 1973 1974 1978 1979 1970 1975 1976 1977

FIGURE 1: INFLATION FORECASTS AND OUTCOMES

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Forecast errors larger in the 70s

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Motivation 2: inflation and misinformation

Orphanides-Williams '02 Percent 10 Forecast Actual 9 u* (Real-Time) u* (Ex-Post) 8 7 6 5 4 3 1969 1970 1971 1972 1973 1974 1975 1976 1977 1978 1979

FIGURE 2: UNEMPLOYMENT FORECASTS AND OUTCOMES

Estimate of natural rate biased. What caused this?

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Related Literature: 'Great Inflation'

- Time inconsistency (Kydland-Prescott)
- Sunspot fluctuations (Clarida-Gali-Gertler, '99 QJE)
- Misspecified model (Sargent '99, Romer-Romer '02)
- Misinformation (Orphanides '01 AER, '02 AER, '03 JME)
- Imperfect credibility (Erceg-Levin, '03 JME)
- This paper is related to Orphanides and Erceg-Levin.
 - Weak nominal anchor disturbs stabilisation policy. How?
 - PS uncertainty about inflation target represents uncertainty facing Central Bank

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Questions addressed

- Unobservable (or incredible) π^*
 - how does this affect private agents?
 - how does this affect central bank?
- What are the interaction between the two?

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Issues

Feedback from private-sector (PS) uncertainty about π^* to monetary policy

- PS belief about π*
 - unobservable to CB
 - CB cannot distinguish from other shocks

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 Expectations formation by PS affected by CB information problem

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Negative feedback on stabilisation an example

Suppose nominal interest rate i_t increases

- Two possibilities ($i_t = r_t + E_{t|\rho} \pi_{t+1}$)
 - inflation expectations increased
 - natural rate increased
- When CB uncertain about PS belief about π*, CB cannot distinguish those two.

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Outline of the model

A simple model of inflation determination

- Flexible prices
- Exogenous output (exogenous natural interest rate = real rate)
- Monetary policy follows a simple rule (No optimisation. Focus on filtering and equilibrium)
- ► π^* unobservable to PS. Perceived target $\pi^*_{t|p}$
- π^{*}_{t|p} unobservable to CB
 (Information structure explained in detail later)

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Results

- Inflation persistence caused by:
 - PS filtering about π^*
 - CB filtering about $\pi^*_{t|p}$ (Recursive nature of filtering)
- Inflation volatility caused by CB's failure to keep track of r_t (Feedback effects of PS uncertainty on stabilisation)
- Persistence and volatility decrease over time
- Weak nominal anchor and MP mistakes are related with each other

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Structural Equations

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Fisher equation

A version of 'expectational' IS curve

$$i_t = r_t + E_{t|p} \pi_{t+1} \tag{IS}$$

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i_t : nominal interest rate; r_t : natural rate; π_t : inflation

- Can be derived from Euler equation under flexible-price equilibrium (Woodford '04, Ch2)
- *E*_{t|p}: expectation operator conditional on PS information

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Monetary policy rule

CB follows a simple rule:

$$i_t = \phi(\pi_t - \pi^*) + \pi^* + E_{t|c}r_t + u_t, \ \phi > 1.$$
 (MP)

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 π^* : inflation target; u_t : monetary policy shock

- $E_{t|c}$: expectation conditional on CB information
- CB wants to keep track of natural rate r_t

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Equilibrium

- Endogenous variables $\{i_t, \pi_t\}_{t=0}^{\infty}$ satisfy (IS) and (MP),
- taking exogenous variables $\{r_t^n, u_t\}_{t=0}^{\infty}$ as given,
- expectations are rational conditional on information set of PS and CB

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Benchmark: When π^* is credible

- π^* is common knowledge
- ► From (IS) and (MP),

$$\pi_t = \pi^* + E_t \sum_{s=0}^{\infty} \phi^{-(s+1)} u_{t+s}$$

• When
$$E_t u_{t+s} = 0$$
 for $s > 1$,

$$\pi_t = \pi^* + \phi^{-1} u_t.$$

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Benchmark: When π^* is credible

Equilibrium is given by

$$\pi_t = \pi^* + \phi^{-1} u_t.$$

- CB fully offsets the effects of r_t on π_t
- Inflation expectations anchored by π^*
- By looking at *i_t*, CB can identify *r_t* even if *r_t* not directly observable.
 (*i_t* = *r_t* + *E_tπ_{t+1}* = *r_t* + π^{*})

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Equilibrium under incredible π^*

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• π^* and u_t : unobservable. PS belief about π^* : denoted by $\pi^*_{t|p}$

• i_t, π_t, r_t, ϕ : observable

► CB belief (*E*_{t|c} π^{*}_{t|p} and *E*_{t|c}r_t): observable (see next page)

Only need to analyse up to 3rd-order belief

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Assumptions on private-sector information

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► r_t , $E_{t|\rho}\pi_{t+1}$, $\pi^*_{t|\rho}$: unobservable

- belief about belief: $E_{t|c}\pi^*_{t|p}$
- belief about rt: Et|crt
- CB announces its belief
 What we have in mind: CB publishes its economic outlook

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• i_t, π_t, u_t, π^* : observable

Assumptions on Central-Bank information

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Normality assumption

 r_t and u_t are iid normal

$$r_t \sim N(0, \sigma_r^2), \ \gamma_r \equiv 1/\sigma_r^2 \text{ (precision)}$$

 $u_t \sim N(0, \sigma_u^2), \ \gamma_u \equiv 1/\sigma_u^2 \text{ (precision)}$

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- Common knowledge
- Can obtain analytical results
- The main results survive if we allow shock-persistence

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$$\pi_t = \phi^{-1} \left[(\phi - 1)\pi^* - u_t + (r_t - E_{t|c}r_t) + E_{t|p}\pi_{t+1} \right]$$

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- $r_t E_{t|c}r_t$: CB estimation error
- Inflation given CB belief

Equilibrium given belief

From (IS) and (MP),

$$\pi_t = \pi^* - \phi^{-1} u_t + \phi^{-1} (E_{t|c} \pi^*_{t|p} - \pi^*).$$

Inflation given PA belief

$$\pi_t = \pi^* - \phi^{-1} u_t + \phi^{-1} (E_{t|p} \pi^* - \pi^*) + E_{t|p} \sum_{j=0}^{\infty} \phi^{-(j+1)} \left[r_{t+j}^n - E_{t+j|c} r_{t+j}^n \right]$$

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2nd order belief matters

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Private-sector filtering

PS observation equation (derived from MP rule)

$$i_t-\phi\pi_t-E_{t|c}r_t=(1-\phi)\pi^*+u_t.$$

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• Observable:
$$z_t \equiv i_t - \phi \pi_t - E_{t|c} r_t$$

Sequential updating of $\pi^*_{t|p}$

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Private-sector filtering

Perceived inflation target after t observations:

$$\pi_{t|p}^{*} - \pi^{*} = b_{t}(\pi_{t-1|p}^{*} - \pi^{*}) + \frac{1 - b_{t}}{1 - \phi}u_{t}, \quad (1)$$

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•
$$b_t \rightarrow 1$$
 as $t \rightarrow \infty$

• Private sector eventually learn π^*

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Equilibrium and CB filtering

Simultaneity

- Equilibrium depends on CB policy
- CB policy depends on CB filtering
- CB filtering depends on statistical relation between observables and unobservables in equilibrium
- Solve by the method of undetermined coefficients (time-varying coefficients).

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CB-filtering about $\pi^*_{t|p}$

Observation equation (Fisher equation)

$$i_t = r_t + E_{t|p} \pi_{t+1}$$

- $E_{t|p}\pi_{t+1}$ is determined simultaneously with CB filtering
- Estimated perceived inflation target

$$E_{t|c}\pi_{t|p}^* - \pi_{t|p}^* = f_t(E_{t-1|c}\pi_{t-1|p}^* - \pi_{t-1|p}^*) + g_t r_t$$
(2)

Estimated natural rate

$$E_{t|c}r_t - r_t = h_t(E_{t-1|c}r_{t-1} - r_{t-1}) + k_tr_t \quad (3)$$

• f_t, g_t, h_t, k_t : time-varying coefficients

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Summary of Equilibrium

Equilibrium is given by

$$\pi_{t} = \underbrace{\pi^{*} - \phi^{-1} u_{t}}_{\bar{\pi}_{t}} + \underbrace{\phi^{-1}(E_{t|c}\pi^{*}_{t|p} - \pi^{*})}_{\tilde{\pi}_{t}}$$

$$\tilde{\pi}_{t} = \phi^{-1} \left\{ \underbrace{(\pi_{t|p}^{*} - \pi^{*})}_{\text{PS uncertainty}} + \underbrace{(E_{t|c}\pi_{t|p}^{*} - \pi_{t|p}^{*})}_{\text{CB uncertainty}} \right\}$$

•
$$(\pi_{t|p}^* - \pi^*)$$
 is given by (1)

•
$$(E_{t|c}\pi^*_{t|p} - \pi^*_{t|p})$$
 is given by (2)

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Implications for great inflation: persistence and volatility

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Inflation dynamics

Our model implies $\tilde{\pi}_t$ is persistence and volatile

- $(E_{t|c}\pi^*_{t|p} \pi^*_{t|p}) \propto (r_t E_{t|c}r_t)$: represents estimation error of r_t .
- persistence: recursive nature of learning.
- ► volatility: Negative feedback of uncertainty about π^* on stabilisation policy

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Great inflation

- High and persistent inflation in the late '70s-early '80s
- Orphanides ('01 AER, '02 AER, '03: JME): Mis-measurement in the output gap/natural interest rate
 - Misinformation is exogenously given.
- Erceg-Levin ('03 JME): weak nominal anchor (imperfect credibility) causes inflation persistence
 - Mainly focuses on persistence but not volatility.

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Great inflation

- This paper connects Orphanides and Erceg-Levin
- Imperfect credibility creates uncertainty about perceived inflation target
- ► → identification of shocks difficult. → source of natural rate mis-measurement
- this causes policy mistakes, generating inflation volatility and persistence.

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Policy implications

- Orphanides
 - Misinformation causes inflation
 - Policy recommendation: avoid responding to noisy estimates of output gap and natural rates

Our paper

- Weak nominal anchor creates misinformation
- Policy recommendation: make nominal anchor strong. If MP becomes credible, misinformation becomes smaller.

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Implications for great moderation: time-varying stochastic properties of inflation

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Time-varying stochastic process of inflation

Our model implies

- $\pi_t \rightarrow \bar{\pi}_t$ as $t \rightarrow \infty$.
- Contribution of $\tilde{\pi}_t$ becomes smaller over time
 - π_t becomes less persistent over time

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• π_t becomes less volatile over time

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Great moderation

 UK inflation: less volatile and less persistent after '92 (Benati '04)

- time-varying stochastic process of π (Cogley-Sargent ('02,'04), Stock-Watson ('02), Ahmed-Levin-Wilson ('04))
- good policy or good luck?
 Existing literature: likely to be good luck.

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Bernanke's conjecture (Bernanke '04 speech)

Econometric methods confuse good policy with good luck

- don't take into account of impact of systematic component of monetary policy on inflation expectations
- fluctuations caused by de-anchored expectations get confused with genuine non-policy shocks

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Reduced-form regression of model-generated data

- Motivated by Stock-Watson (2002), Ahmed-Levin-Wilson (2004) etc
- Estimation of

$$\pi_t = c + \alpha \pi_{t-1} + \varepsilon_t$$

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Reduced-form regression

We are interested in:

- change in α
- change in $SD(\varepsilon_t)$

Literature on 'great moderation' interprets

- change in α as change in propagation
- change in $SD(\varepsilon_t)$ as change in innovation

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Numerical example

•
$$\pi^* = 2, \, \pi^*_{0|p} = 10, \, 0 \le E_{0|c} \pi^*_{0|p} - \pi^*_{0|p} \le 5$$

• $\pi^*_{0|p}$ in line with US estimates in '80-'81 • $E_{0|c}\pi^*_{0|p} - \pi^*_{0|p}$ in line with differences among

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US estimates of perceived target in '80s.

$$\gamma_r = 0.44, \, \gamma_u = 1, \, \phi = 1.5$$

- Simulation for 40 periods, 1000 replications
- Estimate for two sub-samples (1-20, 21-40)
- Sensitivity analysis

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Simulation results



- α and $SD(\varepsilon_t)$ become smaller in the second half
- α and SD(ε_t) become larger as E_{0|c}π^{*}_{0|p} − π^{*}_{0|p}
 becomes larger

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Reduced-form regression of inflation

- Both 'innovation' and 'persistence' decline in reduced-form regression
- But, in our model, policy and structural shocks are constant over time
- In our model, change in stochastic process of π_t is generated by change in expectations (beliefs)
 —- consistent with Bernanke's conjecture

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Summary

 Analysis of uncertainty about perceived inflation target

- Mis-measurement of natural rates endogenously determined
- A unified analysis of weak nominal anchor and misinformation
- Change in stochastic process of inflation driven by changes in expectations — existing literature on Great Moderation has not fully explored yet

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Future work

- Implication for yield curve
 - Excess sensitivity of long rates due to lack of nominal anchor

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How is private-sector inflation expectation affected by CB-uncertainty about perceived target?

$$E_{t|\rho}\pi_{t+1} = (1 - \phi^{-1})\pi_{t|\rho}^* + \phi^{-1}\underbrace{E_{t|\rho}E_{t+1|c}\pi_{t+1|\rho}^*}_{\text{3rd-order belief}}.$$

► In general,
$$E_{t|p}\pi_{t+1} \neq \pi^*_{t|p}$$

 PS expectation about how CB will learn about future n^{*}_{t+1|p} matters

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CB-filtering about $\pi^*_{t|p}$

Observation equation (Fisher equation)

$$i_t = r_t + E_{t|p} \pi_{t+1}$$

 $E_{t|p}\pi_{t+1} = (1 - \phi^{-1})\pi_{t|p}^* + \phi^{-1}E_{t|p}E_{t+1|c}\pi_{t+1|p}^*$

• CB knows $\pi^*_{t|p}$ evolves by:

$$\pi_{t|p}^{*} = a_{t}\pi_{0|p}^{*} + (1 - a_{t})\pi^{*} + \frac{1 - a_{t}}{1 - \phi}\bar{u}_{t} \quad (\text{PSB})$$

 $\pi^*_{0|p}$: only uncertainty to CB

- *E*_{t|ρ}π_{t+1} is determined simultaneously with CB filtering about π^{*}_{0|ρ}
- Solve by the method of undetermined coefficients (time-varying coefficients).

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Equilibrium and CB filtering (1)

Solve by the method of undetermined coefficients.

- Define observables by $X_t \equiv i_t - (1 - a_t)\pi^* - \frac{1 - a_t}{1 - \phi}\bar{u}_t.$
 - Guess:

$$A_t X_t = r_t + B_t \pi^*_{0|p} + C_t E_{t-1|c} \pi^*_{0|p}$$
(G)

 A_t , B_t , C_t to be determined jointly with Kalman filtering about r_t .

• B_t represents the effects of initial perceived target $(\pi^*_{0|p})$ on current equilibrium

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Equilibrium and CB filtering (2)

Derive Kalman filter based on (G), and substitute it back to (G). Then solve for A_t , B_t , C_t . Then B_t satisfies



Once B_t is determined, A_t and C_t are determined.

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Equilibrium and CB filtering (3)

Define new observation equation by

$$Y_t \equiv A_t X_t - C_t E_{t-1|c} \pi^*_{0|p} = \underbrace{r_t + B_t \pi^*_{0|p}}_{\text{unobservable}}.$$

Distribution of Y_t is

$$Y_t \sim N\left(B_t \pi^*_{0|p'} \ \sigma^2_r\right).$$

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Equilibrium and CB filtering (4)

Posterior mean of $B_t \pi^*_{0|p}$ at time *t*:

$$B_t E_{t|c} \pi^*_{0|p} = d_t B_t E_{t-1|c} \pi^*_{0|p} + (1 - d_t) Y_t, \quad (4)$$

where

$$d_{t} \equiv \frac{\frac{B_{t-1}^{2}}{B_{t}^{2}} \tau_{t-1|c}}{\frac{B_{t-1}^{2}}{B_{t}^{2}} \tau_{t-1|c} + \gamma_{r}}$$
(5)

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and
$$\gamma_r \equiv 1/\sigma_r^2$$
.

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Equilibrium properties (1)

- Simultaneity of equilibrium and CB filtering
- ► PS expectations about future CB filtering matters to π_t
- Current CB filtering depends on PS expectations about future CB filtering
- Intuition:
 - Forward-looking nature of inflation
 - Inflation determined by expectations about future MP
 - Future MP depends on future CB filtering

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Equilibrium property (2)

Bt depends on:

- B_{t-1}: recursive nature of filtering
- B_{t+1} : forward-looking nature of inflation
 - π_t depends on PS expectations about future MP
 - future MP depends on filtering d_{t+1}
 - current filtering depends on PS expectations

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EQUILIBRIUM AND CB FILTERING EQUILIBRIUM PROPERTIES SENSITIVITY ANALYSIS Basic results robust against different $\pi^*_{0|p}$, ϕ , γ_u , $\tau_{0|PA}$

- High perceived target (π^{*}_{0|p}) results in high inflation persistence
- Aggressive MP (ϕ) results in smaller SD
- Smaller MP shock (larger γ_u) results in smaller SD and less persistence (because PS learning is quicker)
- More stubborn belief (larger \u03c6_{0|PA}) results in larger SD and more persistence (because PS learning is slower)

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Sensitivity analysis (1)

Benchmark ($\pi^*_{0PA} = 10$, Black line) vs. Higher perceived target ($\pi^*_{0PA} = 20$, Gray line)



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Sensitivity analysis (2)

Benchmark ($\phi = 1.5$, Black line) vs. Less aggressive monetary policy ($\phi = 1.1$, Gray line)



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Sensitivity analysis (3)

Benchmark ($\gamma_u = 1$, Black line) vs. Smaller monetary policy shock ($\gamma_u = 4$, Gray line)



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Sensitivity analysis (4)

Benchmark ($\tau_{\alpha_{PA}} = 1$, Black line) vs. More stubborn belief ($\tau_{\alpha_{PA}} = 10$, Gray line)



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