CIRJE-F-248

An Asymptotic Expansion Scheme for the Optimal Investment Problems

Akihiko Takahashi
Nakahiro Yoshida
The University of Tokyo

November 2003
An Asymptotic Expansion Scheme for the Optimal Investment Problems

Akihiko Takahashi and Nakahiro Yoshida

Graduate School of Mathematical Sciences, University of Tokyo,
3-8-1 Komaba, Meguro-ku, Tokyo 153, Japan.

November, 2003

Abstract

We shall propose a new computational scheme for the evaluation of the optimal portfolio for investment. Our method is based on an extension of the asymptotic expansion approach which has been recently developed for pricing problems of the contingent claims’ analysis by Kunitomo-Takahashi (1992, 1995, 1998, 2001), Yoshida (1992), Takahashi (1995, 1999), Takahashi and Yoshida (2001). In particular, we will explicitly derive a formula of the optimal portfolio associated with maximizing utility from terminal wealth in a financial market with Markovian coefficients, and give a numerical example for a power utility function.

(Forthcoming in “Statistical Inference for Stochastic Processes”.)
1 Introduction

We shall propose a new computational scheme for the evaluation of the optimal portfolios for investment. Our method is based on the asymptotic expansion approach, a unified method of efficient computation justified by Malliavin-Watanabe(1987) theory, which has been recently developed for pricing problems of the contingent claims' analysis by Kunitomo-Takahashi(1992,1995,1998,2001,2003), Yoshida(1992), Takahashi(1995,1999), Kunitomo and Kim(1999), Sorensen and Yoshida(1998), and Takahashi and Yoshida(2001). They have developed the method through deriving formulas for practical examples such as average options, basket options, and options with stochastic volatility and with stochastic interest rates in a Markovian setting, as well as bond options(swaptions), average options on interest rates, and average options on foreign exchange rates with stochastic interest rates in the Heath-Jarrow-Morton(1992) framework. In this paper, we extend the method to portfolio problems. In particular, we will explicitly derive the formula of the optimal portfolio associated with maximizing utility from terminal wealth in a complete market, where the short term risk-free rate and the market price of risk are described by some functions of a random vector following a multi-dimensional Markov process. Moreover, we provide numerical examples for power utility functions. In general, it is quite difficult to compute an optimal portfolio explicitly when the investment oppotunity is stochastic in a multiperiod setting. The stochastic control approach initiated by Merton(1969,1971) gives a solution in terms of the derivatives of the value function: While the solution can be evaluated numerically based on the Hamilton-Jacobi-Bellman equation, the implementation is not easy especially for the case of multiple assets. In the martingale approach initiated by Karatzas et al.(1987) and Cox and Huang(1989), Ocone and Karatzas(1991) proposed the representation of optimal portfolios by utilizing the Clark formula. Although their representation formulas were derived in general setting, explicit evaluation was obtained only for logarithmic utility functions or a financial market with deterministic coefficients, which were already known without their formulas. Starting with the Clark formula, we will present an explicit expression for the optimal portfolio in a concrete and important setting where key variables such as the short term risk-free rate and the market price of risk are some functions of a random vector whose evolution is described by a multi-dimensional Markov process. Moreover, our method can be easily extended to the optimal portfolios associated with maximizing utility from both consumption and terminal wealth, and to the hedging portfolios associated with contingent claims. Regarding the related works, Detemple et al.(2000) utilizes Monte Carlo simulations to investigate optimal portfolios for a power utility function in several Markovian examples. The organization of this paper is as follows. In section 2 we explain the problem of the optimal portfolio for investment and restate the problem in a Markovian setting. In section 3 we briefly explain basic tools for an asymptotic expansion approach. In section 4, we illustrate our method using a power utility function, and derive the second order scheme explicitly. In section 5 we also derive the second order scheme for general utility functions.
In section 6 we give a numerical example. Finally, in appendix, we provide proofs of lemmas, show the result of the third order scheme for power utility functions, and discuss the validity of our method for the numerical example considered in Section 6.

2 Representation of Optimal Portfolio

2.1 Representation of Optimal Portfolio for Investment

We will briefly describe the financial market and introduce the representation of the optimal portfolio for investment derived by Ocone and Karatzas (1991).

We start with basic setup of the financial market. Let \((\Omega, \mathcal{F}, P)\) probability space and \(T \in (0, \infty)\) denotes some fixed time horizon of the economy. \(w(t) = (w^1(t), \ldots, w^r(t))^*\), \(0 \leq t \leq T\) is \(\mathbb{R}^r\)-valued Brownian motion defined on \((\Omega, \mathcal{F}, P)\) and \(\{\mathcal{F}_t\}, 0 \leq t \leq T\) stands for \(P\)-augmentation of the natural filtration, \(\mathcal{F}_t^w = \sigma(w(s); 0 \leq s \leq t)\). Here, we use the notation of \(x^*\) as the transpose of \(x\). \(S_i(t), i = 1, \ldots, r\) and \(S_0(t)\) denote the prices at time \(t \in [0, T]\) of the risky asset \(i\) and of the riskless asset respectively. The prices are assumed to follow the stochastic processes: For \(t \in [0, T]\),

\[
\begin{align*}
    dS_i &= S_i(t)[b_i(t)dt + \sum_{j=1}^r \sigma_{ij}(t)dw_j(t)], \quad S_i(0) = s_i, \quad i = 1, \ldots, r \\
    dS_0 &= r(t)S_0(t)dt, \quad S_0(0) = 1,
\end{align*}
\]

where we suppose that \(r(t), b_i(t)\) and \(\sigma_{ij}(t), i, j = 1, \ldots, r\) are bounded and progressively measurable with respect to \(\{\mathcal{F}_t\}\). We also assume the nondegeneracy condition; for the \(r \times r\) matrix \(\sigma(t) \equiv \{\sigma_{ij}(t)\}_{1 \leq i, j \leq r}\) there exists a real number \(\varepsilon > 0\) such that

\[
\xi^*\sigma(t, \omega)\sigma(t, \omega)^*\xi \geq \varepsilon|\xi|^2; \quad \forall \xi \in \mathbb{R}^r, \quad (t, \omega) \in [0, T] \times \Omega.
\]

Then, the stochastic process of an investor’s wealth denoted by \(W(t)\) are expressed as

\[
    dW(t) = [r(t)W(t) - c(t)]dt + \pi(t)^*[\{b(t) - r(t)1\}dt + \sigma(t)dw(t)] \quad (2)
\]

where \(W(0) = W > 0\) is the initial capital, \(1\) denotes the vector in \(\mathbb{R}^r\) with all elements equal to 1, \(c(t)\) denotes the consumption rate, \(b(t) = (b_1(t), \ldots, b_r(t))^*\), and \(\pi(t) = \{\pi_i(t)\}_{i=1,\ldots,r}\) denotes the portfolio. \(c(t)\) and \(\pi(t)\) satisfy the integrability condition;

\[
\int_0^T \{||\pi(t)||^2 + c(t)\}dt < \infty \quad a.s.
\]

Next, let \(\mathcal{A}(W)\) denote the set of stochastic processes \((\pi, c)\) which generate \(W(t) \geq 0\) for all \(t \in [0, T]\) given \(W(0) = W\). We call \((\pi, c)\) is admissible for \(W\) if \((\pi, c) \in \mathcal{A}(W)\).

The problem of maximizing utility from terminal wealth is formulated as follows: With \(c \equiv 0\),

\[
\sup_{(\pi, c) \in \mathcal{A}(W)} E[U(W(T))] \quad (3)
\]
where \( E[\cdot] \) denotes the expectation operator under \( P \), and \( U \) denotes a utility function such that

\[
U : (0, \infty) \to \mathbb{R},
\]

a strictly increasing, strictly concave function of class \( C^2 \)

with \( U(0+) \equiv \lim_{c \to 0} U(c) \in [-\infty, \infty), \ U'(0+) \equiv \lim_{c \to 0} U'(c) = \infty \)

and \( U'(\infty) \equiv \lim_{c \to \infty} U'(c) = 0 \).

Let the market price of risk \( \theta(t) \) for \( t \in [0, T] \) an \( \mathbb{R}^r \)-valued progressively measurable bounded process defined by

\[
\theta(t) = \sigma(t)^{-1}[b(t) - r(t)]1.
\]

Then, the martingale measure denoted by \( P_0 \) is defined as \( P_0(A) = E[1_A Z(T)] \) for all \( A \in \mathcal{F}_T \) where

\[
Z(t) = \exp \left(-\int_0^t \theta(s)^*dw(s) - \frac{1}{2} \int_0^t |\theta(s)|^2ds\right) : 0 \leq t \leq T.
\]

We note that \( w_0(t) = w(t) + \int_0^t \theta(u)du \) for \( 0 \leq t \leq T \) is a standard Brownian motion under \( P_0 \).

Regarding the problem of maximizing utility from terminal wealth, it is well known that the optimal wealth level of terminal wealth given by \( W(T) = I(Y(W)H_0(T)) \) and that the value function \( V(W) := \sup_{(\pi,c) \in \mathcal{A}(W)} E[U(W(T))] \)

can be computed as \( V(W) = G(Y(W)) \), where \( G(y) := E[U(I(yH_0(T)))] \); \( 0 < y < \infty \). (See for instance Theorem 7.6 in Karatzas and Shreve(1998) pp.114.) Here, a continuously differentiable function \( I : (0, \infty) \to (0, \infty) \) (which is expressed as \( I \in C^1((0, \infty); (0, \infty)) \)) denotes the inverse of \( U'(-), b \) and \( Y(-) \) denotes the inverse of the continuous decreasing function:

\[
X(y) = E_0[\beta(T)I(yH_0(T))] = E[H_0(T)I(yH_0(T))]; 0 < y < \infty
\]

which we assume maps \( (0, \infty) \) into \( (0, \infty) \), where \( \beta(t) \equiv 1/S_0(t), H_0(t) \equiv \beta(t)Z(t) \) denotes the state price density at \( t \) and \( E_0[\cdot] \) denotes the expectation operator under \( P_0 \).

Ocone and Karatzas(91) provides the following theorem by utilizing the Clark formula regarding the problem of the optimal portfolio for investment associated with maximizing utility from terminal wealth.

**Theorem[Ocone and Karatzas(91)]**

*Suppose that a utility function satisfies the conditions (4) and that

\[
I(y) + |I'(y)| \leq K(y^\alpha + y^{-\beta}), \ 0 < y < \infty
\]

holds for some real positive constants \( \alpha, \beta \) and \( K \). Then the optimal portfolio admits the representation:

\[
\pi^*(t) \sigma(t) = -\frac{1}{\beta(t)} \{ \theta^*(t)E_0[\beta(T)Y(W)H_0(T)I'(Y(W)H_0(T))]|\mathcal{F}_t] \}
\]

(5)*
\[
\pi^* \sigma(t) = \left\{ W(t) - \mathbb{E} \left[ \frac{H_0(t)}{H_0(T)} \phi'(\mathcal{Y}(W)H_0(T)) | F_t \right] \phi'(\mathcal{Y}(W)H_0(T)) \right\} \theta^*(t)
\]

where \( \phi(y) \equiv y I(y), \) \( 0 < y < \infty, \) and \( D_t r(u) \) and \( D_t \theta_\alpha(u) \) for \( \alpha = 1, 2, \ldots, r \) denote the Malliavin derivatives of \( r(u) \) and \( \theta_\alpha(u) \).

Here we suppose that \( \theta \) and \( r \) satisfy the following conditions:

1. **R**-valued progressively measurable process \( r \) is bounded; for a.e. \( s \in [0, T] \) \( r(s, \cdot) \in D_{1,1} \) where \( D_{1,1} \) denotes the Sobolev space \( D_{p,s} \) with \( (p, s) = (1, 1) \), \( (s, \omega) \to Dr(s, \omega) \in (L^2([0, T]))^r \) admits progressively measurable version, and

\[
\|r\|^2_{1,1} \equiv \mathbb{E} \left[ \left( \int_0^T |r(s)|^2 ds \right)^\frac{1}{2} + \left( \int_0^T \|Dr(s)\|^2 ds \right)^\frac{1}{2} \right] < \infty
\]

where \( \|\cdot\| \) denotes the \( L^2([0, T]) \) norm, and \( \|Dr(s)\|^2 \equiv \sum_{i=1}^r \|D^i r(s)\|^2 \).

2. **R**'-valued progressively measurable process \( \theta \) is bounded; for a.e. \( s \in [0, T] \) \( \theta(s, \cdot) \in (D_{1,1})^r \), \( (s, \omega) \to D\theta(s, \omega) \in (L^2([0, T]))^r \) admits a progressively measurable version, and

\[
\|\theta\|^2_{1,1} \equiv \mathbb{E} \left[ \left( \int_0^T |\theta(s)|^2 ds \right)^\frac{1}{2} + \left( \int_0^T \|D\theta(s)\|^2 ds \right)^\frac{1}{2} \right] < \infty
\]

where \( \|D\theta(s)\|^2 \equiv \sum_{j=1}^r \|D^j \theta_j(s)\|^2 \).

3. For some \( p > 1 \) we have

\[
\mathbb{E} \left[ \left( \int_0^T \|Dr(s)\|^2 ds \right)^\frac{p}{2} \right] < \infty, \quad \mathbb{E} \left[ \left( \int_0^T \|D\theta(s)\|^2 ds \right)^\frac{p}{2} \right] < \infty.
\]

**Proof.** See theorem 4.2 of Ocone and Karatzas(91).

More intuitive formula can be obtained under original measure \( P \).

**Theorem 1** Under the same conditions as in theorem [Ocone and Karatzas(91)], the optimal portfolio has the representation under measure \( P \):

\[
\pi^* \sigma(t) = \left\{ W(t) - \mathbb{E} \left[ \frac{H_0(T)}{H_0(t)} \phi'(\mathcal{Y}(W)H_0(T)) | F_t \right] \right\} \theta^*(t)
\]

\[
-\mathbb{E} \left[ \frac{H_0(T)}{H_0(t)} \phi'(\mathcal{Y}(W)H_0(T)) \times \left( \int_0^T D_t r(u)du + \sum_{\alpha=1}^r \left\{ \int_t^T D_t \theta_\alpha(u) du \theta_\alpha(u) + \int_t^T D_t \theta_\alpha(u) \theta_\alpha(u) du \right\} \right] | F_t \right\}
\]

where \( W(t) \) denotes the optimal wealth at time \( t \), and is determined by

\[
W(t) = \mathbb{E} \left[ \frac{H_0(T)}{H_0(t)} I(\mathcal{Y}(W)H_0(T)) | F_t \right].
\]
Proof. The relation (7) is well known. (See theorem 7.6 of Karatzas and Shreve(98) for instance.) Rewrite the equation (5) under $P$ by using (7),

$$\phi'(y) = I(y) + yI'(y),$$

and $w_0(t) = w(t) + \int_0^t \theta(u)du$ to obtain the result.

In the optimal portfolio of the equation (6), the first term on the right hand side represents the optimal portfolio in one-period setting that is sometimes called mean-variance portfolio, while the second term is specific to multi-period setting, which Merton(71) named *hedging demand* in a sense that the term represents demand for hedging against randomness in the future; specifically, the terms $D_tr(u)$ and $D_t\theta_\alpha(u)$ express the changes of interest rate and market price of risk in the future respectively.

It is well known that the optimal portfolio $\pi(t)$ is easily derived for two simple cases: (See for instance chapter 3 in Karatzas and Shreve(1998).) For the case of a log utility function $U(x) = \log x$,

$$\pi^*(t) = \theta^*(t)\sigma(t)^{-1}W(t)$$

where $\theta(t) = \sigma(t)^{-1}[b(t) - r(t)1]$, since $\phi \equiv 1$ and hence $\phi' \equiv 0$. This is exactly same as mean-variance portfolio in one-period portfolio problem; that is, the optimal portfolio per wealth is given by the vector of the excess expected returns of risky assets over the riskless asset multiplied by variance matrix. In this sense, an investor with a log utility is sometimes called a myopic investor. For the case of a power utility function defined by $U(x) = x^\delta$, $\delta < 1, \delta \neq 0$ for $x \in (0, \infty)$, if $r(\cdot)$ and $\theta(\cdot)$ are deterministic,

$$\pi^*(t) = \frac{1}{(1 - \delta)} \theta^*(t)\sigma(t)^{-1}W(t)$$

because $D_tr(u) \equiv 0$ and $D_t\theta_\alpha(u) \equiv 0$. However, if $r(\cdot)$ and $\theta(\cdot)$ are not deterministic, it is not easy to evaluate $\pi(t)$ explicitly for a power utility function.

### 2.2 Optimal Portfolio for Investment in a Markovian Setting

In the spirit of Ocone and Karatzas (1991), we will consider more concrete and important setting for practical purpose in the sequel.

From now on, we will consider a Wiener space on $[t, T]$ for some fixed $t \in [0, T]$ and assume that all random variables will be defined on it. Let $X^\epsilon_u$ be a $d$-dimensional diffusion process defined by the stochastic differential equation:

$$dX^\epsilon_u = V_0(X^\epsilon_u, \epsilon)du + V(X^\epsilon_u, \epsilon)dw_u, \quad X^\epsilon_t = x$$

for $u \in [t, T]$. Here we suppose that $\epsilon \in (0, 1]$ denotes a parameter used as the asymptotic expansion, $V_0 \in C^\infty_b(\mathbb{R}_d \times (0, 1]; \mathbb{R}_d)$ and $V = (V_\beta)_{\beta=1}^r \in C^\infty_b(\mathbb{R}_d \times (0, 1]; \mathbb{R}_d \otimes \mathbb{R}_r)$ where $C^\infty_b(\mathbb{R}_d \times (0, 1]; E)$ denotes a class of smooth mappings $f : \mathbb{R}_d \times (0, 1] \to E$ whose derivatives $\partial^m_x \partial^m_\epsilon f(x, \epsilon)$ are all bounded.
for \( n \in \mathbb{Z}_+^d \) such that \( |n| \geq 1 \) and \( m \in \mathbb{Z}_+^d \). Note that time-dependent-coefficient diffusion processes are included in the above equation if we enlarge the process to a higher-dimensional one. We also assume the bounded processes \( r(u) \) and \( \theta(u) \) to be \( r(u) = r(X_u^t) \) and \( \theta(u) = \theta(X_u^t) \) where \( r \in C^\infty_b(\mathbb{R}^d; \mathbb{R}_+) \) and \( \theta \in C^\infty_b(\mathbb{R}^d; \mathbb{R}) \). We remark that our framework includes a financial market with Markovian coefficients of return processes as a special case, in which not only \( r(u) \) but also \( b(u) \) and \( \sigma(u) \) are some functions of \( X_u^t \).

Let \( Y_{t,u}^\epsilon \) be a unique solution of the \( d \times d \)-matrix valued stochastic differential equation:

\[
\begin{align*}
\frac{dY_{t,u}^\epsilon}{du} &= \sum_{\alpha=0}^r \partial_x V_{\alpha}(X_{t,u}^\epsilon, \epsilon) Y_{t,u}^\epsilon dw_{\alpha} \\
Y_{t,t}^\epsilon &= I
\end{align*}
\]

(10)

Then, we have the representation of the optimal portfolio \( \pi(t) \) in our Markovian setting, which is stated as a corollary of theorem 1:

**Corollary 1.1** The optimal portfolio under the Markovian setting (9) and (10) is represented as follows.

\[
\pi^*(t)(x) = \left\{ W - \mathbb{E} \left[ H_{0,t,T} \phi'(\mathcal{Y}H_{0,t,T}) \right] \right\} \theta^*(x)
\]

(11)

where \( W \) is a given wealth at time \( t \), \( H_{0,t,T} \) is defined by

\[
H_{0,t,T} = \frac{H_0(T)}{H_0(t)} = \exp \left( - \int_t^T \theta(X_u^t) dw(u) - \frac{1}{2} \int_t^T |\theta(X_u^t)|^2 du - \int_t^T r(X_u^t) du \right),
\]

and \( \mathcal{Y} \) is determined by the equation:

\[
W = \mathbb{E}[H_{0,t,T} I(\mathcal{Y}H_{0,t,T})].
\]

(12)

**Proof.** It is well known that

\[
D_t X_u^\epsilon = Y_{t,u}^\epsilon V(X_t^\epsilon, \epsilon) = Y_{t,u}^\epsilon V(x_t, \epsilon), \quad u \geq t,
\]

and that

\[
D_t f(X_u^t) = \partial f(X_u^t)[D_t X_u^t] = \partial f(X_u^t) Y_{t,u}^\epsilon V(x_t, \epsilon); \quad u \geq t,
\]
for $f \in C_0^\infty(\mathbb{R}^d; \mathbb{R})$. Apply those facts to the equation (6) with $f(\cdot) \equiv r(\cdot)$ or $\theta(\cdot)$.

Our objective is to evaluate $\pi(t)$ explicitly. It is possible to compute $\pi(t)$ based on a Monte Carlo simulation. However, it is path-dependent, besides, the functions $\phi'$ is often irregular, and the error bounds are not yet fully investigated in such a situation, while Kohatsu and Yoshida (2001) recently provided an error bound to the Euler-Maruyama scheme for path-dependent functionals. Moreover, Monte-Carlo methods are not so useful from a computational viewpoint when a family of stochastic differential equations is treated; especially, the sensitivity analysis which controls the underlying stochastic differential equations is the case.

In the present article, we will propose a practical and more efficient scheme for computing the optimal portfolio by utilizing the asymptotic expansion approach. On the asymptotic expansion approach, first-order asymptotics was proposed in Kunitomo-Takahashi (1992) for geometric Brownian motion. In order to obtain more precise approximation, the asymptotic expansion method was introduced with the Malliavin calculus and investigated for the evaluation of path-dependent contingent claims in Yoshida (1992), Takahashi (1995, 1999), Kunitomo and Takahashi (1995, 1998, 2001), Kunitomo and Kim (1999), and Takahashi and Yoshida (2001).

3 An Asymptotic Expansion Scheme

We will introduce basic tools for an asymptotic expansion scheme. First, we will derive the asymptotic expansions of $X^0_u$ and $Y^r_{t,u}$ in (9) and (10) respectively which will provide the basis for the subsequent analysis. We start with a basic assumption, the deterministic limit condition:

[A1] $V(\cdot, 0) \equiv 0$.

It follows from [A1] that the limit process $(X^0_u)_{u \in [t,T]}$ is a unique deterministic solution of the ordinary differential equation:

\[
X^0_u = x + \int_t^u V_0(X^0_s, 0) ds.  \tag{13}
\]

We further assume $\sigma(X^0_u)$ is non-singular for all $u \in [t, T]$. Next, put $Y_{t,s} := Y^0_{t,s}$ and then clearly, $Y_{t,s}$ is a unique deterministic solution of the ordinary differential equation:

\[
dY_{t,s} = \partial_x V_0(X^0_s, 0) Y_{t,s} ds  \quad s \in [t, T].
\]

\[
Y_{t,t} = \mathbb{I}
\]

where $Y_{t,s} \in GL(d, \mathbb{R})$. Next, let $D(t; u) = \frac{\partial X_u}{\partial \epsilon}|_{\epsilon=0}$, $E(t; u) = \frac{\partial^2 X_u}{\partial \epsilon^2}|_{\epsilon=0}$ and $Y^r_{t,u} = \frac{\partial Y^r_{t,u}}{\partial \epsilon}|_{\epsilon=0}$. Then $D(t; u)$, $E(t; u)$ and $Y^r_{t,u}$ ($u \in [t, T]$) are determined by the following stochastic differential equations:

\[
\begin{cases}
dD(t; u) = \partial_x V_0(X^0_u, 0) D(t; u) du + \sum_{\alpha=0}^r \partial \alpha V_0(X^0_u, 0) dw^\alpha \\
D(t; t) = 0,
\end{cases}
\]

\[
\tag{15}
\]
Lemma 1 The asymptotic expansions of $X^\epsilon_u$ and $Y^\epsilon_{t,u}$ are obtained as follows:

$$X^\epsilon_u = X_u + \epsilon D(t; u) + \frac{\epsilon^2}{2} E(t; u) + o(\epsilon^2)$$

and

$$Y^\epsilon_{t,u} = Y_{t,u} + \epsilon Y^1_{t,u} + o(\epsilon),$$

where

\[
\begin{align*}
D(t; u) &= Y_{t,u} \int_t^u Y_{t,s}^{-1} \sum_{\alpha=0}^{r} \partial_\epsilon V_{\alpha s} dw_s^\alpha \\
E(t; u) &= Y_{t,u} \int_t^u Y_{t,s}^{-1} \left\{ \partial^2 V_{0s} [D(t; s), D(t; s)] ds + 2 \sum_{\alpha=0}^{r} \partial_\epsilon V_{\alpha s} D(t; s) dw^\alpha + \sum_{\alpha=0}^{r} \partial_\epsilon^2 V_{\alpha s} dw^\alpha \right\} \\
Y^1_{t,u} &= Y_{t,u} \int_t^u (Y_{t,s})^{-1} \left[ \partial^2 V_{0s} [D(t; s)] Y_{t,s} ds + \sum_{\alpha=0}^{r} \partial_\epsilon V_{\alpha s} Y_{t,s} dw_s^\alpha \right].
\end{align*}
\]
Next, we will consider the asymptotic expansion of the following functional which will appear frequently in the sequel. Define

\[ \zeta_{t,u}^\epsilon := \exp \left( \int_t^u a_0(X_s^\epsilon)ds + \int_t^u a(X_s^\epsilon)dw_s \right), \tag{18} \]

where \( a_0 \in C^\infty_\uparrow(\mathbb{R}^d; \mathbb{R}) \) and \( a \in C^\infty_\uparrow(\mathbb{R}^d; \mathbb{R}^r) \). Here, \( C^\infty_\uparrow(\mathbb{R}^d; \mathbb{R})(C^\infty_\uparrow(\mathbb{R}^d; \mathbb{R}^r)) \) denotes a class of smooth functions \( f : \mathbb{R}^d \to \mathbb{R} \) (\( f : \mathbb{R}^d \to \mathbb{R}^r \)) whose derivatives are of polynomial growth orders. In addition, we assume the following integrability condition for \( \zeta_{t,T}^\epsilon \):

\[ [A2] \text{For any } p \in (1, \infty), \sup_{\epsilon \in (0,1]} \left\| \zeta_{t,T}^\epsilon \right\|_p < \infty. \]

Then, we easily obtain the next lemma.

**Lemma 2** Under Condition \([A2]\), \( \zeta_{t,T}^\epsilon \) has an asymptotic expansion:

\[ \zeta_{t,T}^\epsilon \sim \zeta_{t,T}^0 + \epsilon \zeta_{t,T}^{[1]} + \frac{\epsilon^2}{2} \zeta_{t,T}^{[2]} + \cdots \tag{19} \]

in \( L^p \) for every \( p > 1 \) (or in \( D^\infty \)) as \( \epsilon \downarrow 0 \). The first three coefficients are given by

\[
\begin{align*}
\zeta_{t,T}^0 &= \exp \left( \int_t^T a_0(X_s)d\sigma + \int_t^T a(X_s)dw_s \right), \\
\zeta_{t,T}^{[1]} &= \zeta_{t,T}^0 \left( \int_t^T \partial_x a_0(X_s)D(t; s)ds + \int_t^T \partial_x a(X_s)D(t; s)dw_s \right), \\
\zeta_{t,T}^{[2]} &= \zeta_{t,T}^0 \left\{ \int_t^T \partial_x a_0(X_s)D(t; s)ds + \int_t^T \partial_x a(X_s)D(t; s)dw_s \right. \\
& \quad + \int_t^T \partial_x a_0(X_s)E(t; s)ds + \int_t^T \partial_x a(X_s)E(t; s)dw_s \\
& \quad + \int_t^T \partial_{xx} a_0(X_s)[D(t; s), D(t; s)]ds + \int_t^T \partial_{xx} a(X_s)[D(t; s), D(t; s)]dw_s \right\}. 
\end{align*}
\]

**Proof.** Taylor expansion under the integrability condition \([A2]\) gives the result.

Finally in this section, we will derive an expansion of the following functional which will be frequently used in the subsequent analysis:

\[ g^{\alpha,\epsilon} = \int_t^T \partial f(X_u^\epsilon)Y_{t,u}^\epsilon V(x_t, \epsilon)dw_u^\alpha, \quad \alpha = 0, 1, \cdots, r. \tag{20} \]

where \( f \in C^\infty_\uparrow(\mathbb{R}^d; \mathbb{R}) \).
Lemma 3 The asymptotic expansion of $g^{\alpha,\epsilon}$ is given by

$$g^{\alpha,\epsilon} \sim \epsilon g^{\alpha,[1]} + \frac{\epsilon^2}{2} g^{\alpha,[2]} + \ldots$$

in $L^p$ for every $p > 1$ (or in $D^\infty(R^d)$) as $\epsilon \downarrow 0$. Here, $g^{\alpha,[i]}$, $i = j = 1, 2$ denote the first derivative $g^{\alpha,[1]} \equiv \frac{\partial g^{\alpha,\epsilon}}{\partial \epsilon}|_{\epsilon=0}$ and the second derivative $g^{\alpha,[2]} \equiv \frac{\partial^2 g^{\alpha,\epsilon}}{\partial \epsilon^2}|_{\epsilon=0}$ of $g^{\alpha,\epsilon}$ respectively, and they are expressed as follows:

$$g^{\alpha,[1]} = \int_t^T \partial_x f(X_u)Y_{t,u} \partial_t V(x_t,0)dw_u^\alpha$$

$$g^{\alpha,[2]} = 2 \int_t^T \sum_{i=1}^d \sum_{j=1}^d \partial_i \partial_j f(X_u)D^{(j)}(t;u)Y_{t,u}^{(i,\cdot)} \partial_t V(x_t,0)dw_u^\alpha$$

$$+ 2 \int_t^T \sum_{i=1}^d \partial_i f(X_u)Y_{t,u}^{[1] ,(\cdot)} \partial_x V(x_t,0)dw_u^\alpha$$

$$+ \int_t^T \sum_{i=1}^d \partial_i f(X_u)Y_{t,u}^{R^{(\cdot)}} \partial^2_t V(x_t,0)dw_u^\alpha.$$ (21)

Proof. See appendix.

4 The Scheme for Power Utility Functions

4.1 Power Utility Functions

In this section, we will illustrate our approach through an asymptotic expansion of the optimal portfolio for power utility functions. We first assume that a utility function in (4) is specified as so-called a power function; that is

$$U(x) = \frac{x^\delta}{\delta}, \quad x \in (0, \infty), \delta < 1, \delta \neq 0.$$ (22)

Then, $I(y)$ and $\phi(y)$ are given by $I(y) = y^{\frac{1}{1-\delta}}$, $\phi(y) = y^{\frac{\delta}{1-\delta}}$ and $\phi'(y) = \frac{-\delta}{(1-\delta)}I(y)$.

Hence, in this case the optimal portfolio given in the equation (11) is expressed as follows;

$$\pi^*(t)\sigma(x) = \frac{1}{(1-\delta)} W\theta(x)^* + \frac{\delta}{(1-\delta)} (Y) \left[ (H_{0,t,T})^{-\frac{\delta}{1-\delta}} \right]$$

$$\left[ \int_t^T \partial r(X_u^\epsilon)Y_{t,u}^\epsilon V(x,\epsilon)du + \sum_{\alpha=1}^r \int_t^T \partial \theta^\alpha(X_u^\epsilon)Y_{t,u}^\epsilon V(x,\epsilon)du \right]$$

$$+ \sum_{\alpha=1}^r \int_t^T \theta^\alpha(X_u^\epsilon)\partial \theta^\alpha(X_u^\epsilon)Y_{t,u}^\epsilon V(x,\epsilon)du$$

where

$$W = (Y)^{\frac{1}{1-\delta}} \left[ (H_{0,t,T})^{-\frac{\delta}{1-\delta}} \right].$$

Here, we use the abbreviations $r(u) = r(X_u^\epsilon)$ and $\theta^\alpha(u) = \theta^\alpha(X_u^\epsilon)$. We also notice that $(Y)^{\frac{1}{1-\delta}}$ is expressed explicitly in terms of the current wealth.
Then, alternatively, the optimal proportions of risky assets in wealth denoted by \( \pi^*(t)/W \) are given as follows:

\[
\pi^*(t)/W = \frac{1}{(1-\delta)} \theta(x)^* \sigma^{-1}(x) + \frac{\delta}{(1-\delta)} \mathbb{E} \left[ (H_{0,t,T})^{\frac{1}{1-\delta}} \right] \times \\
\mathbb{E} \left[ (H_{0,t,T})^{\frac{1}{1-\delta}} \left( \int_t^T \partial r(X^t_u)Y^t_{t,u} V(x, \epsilon) du + \sum_{\alpha=1}^r \int_t^T \partial \theta^\alpha(X^t_u)Y^t_{t,u} V(x, \epsilon) dw^\alpha(u) \right) \right] \sigma^{-1}(x).
\]

We remark that the equation (8) which represents the optimal portfolio when \( r(\cdot) \) and \( \theta(\cdot) \) are not random does not have the second term on the right hand side of the equation (24), because in that case,

\[
\partial r(u) = \partial \theta^\alpha(u) \equiv 0.
\]

Hereafter, our objective is to derive an asymptotic expansion of the equation (24); Because the first term on the right hand side of the equation (24) is already obtained explicitly by the current information at time \( t \), we will derive an asymptotic expansion of the second term applying the technique prepared in the previous section. More specifically, we will consider the term \( E \) defined as follows;

\[
E \equiv \frac{1}{\mathbb{E} \left[ (H_{0,t,T})^{\frac{1}{1-\delta}} \right]} \mathbb{E} \left[ (H_{0,t,T})^{\frac{1}{1-\delta}} \left( \int_t^T \partial r(X^t_u)Y^t_{t,u} V(x, \epsilon) du + \sum_{\alpha=1}^r \int_t^T \partial \theta^\alpha(X^t_u)Y^t_{t,u} V(x, \epsilon) dw^\alpha(u) \right) \right] \sigma^{-1}(x).
\]

### 4.2 Preparations

First, we notice that we can directly apply the expression (19) in lemma 2 to \( (H_{0,t,T})^{\frac{1}{1-\delta}} \) in the equation (24) if we set \( \zeta^t_{t,u} \equiv (H_{0,t,T})^{\frac{1}{1-\delta}} \), and specify \( a_0(X^t_s) \) and \( a(X^t_s) \) as

\[
a_0(X^t_s) = \left( \frac{\delta}{1-\delta} \right) r(X^t_s) + \frac{\delta}{2(1-\delta)} |\theta(X^t_s)|^2 \\
\text{and} \quad a(X^t_s) = \left( \frac{\delta}{1-\delta} \right) \theta^\alpha(X^t_s).
\]

Here, we note that [A2] is satisfied in this case because of the boundedness assumptions of \( r(\cdot) \) and \( \theta(\cdot) \).
Next, we will show the following expansions;

\[
\begin{align*}
g^\varepsilon_r &= \int_t^T \partial r(u) Y_{t,u} V(x, \varepsilon) du \\
g^{\alpha,\varepsilon}_\theta &= \int_t^T \partial \theta_\alpha(u) Y_{t,u} V(x, \varepsilon) du \\
g^{\alpha,\varepsilon}_\varepsilon &= \int_t^T \theta_\alpha(u) \partial \theta_\alpha(u) Y_{t,u} V(x, \varepsilon) du,
\end{align*}
\]

which appear in the second term of the equation (24).

**Lemma 4** The asymptotic expansion of \(g^\varepsilon_r\), \(g^{\alpha,\varepsilon}_\theta\), and \(g^{\alpha,\varepsilon}_\varepsilon\) defined in (26) upto the \(\varepsilon^2\)-order are obtained as follows:

\[
\begin{align*}
g^\varepsilon_r &= \varepsilon g^{[1]}_r + \frac{\varepsilon^2}{2} g^{[2]}_r + o(\varepsilon^2) \\
g^{\alpha,\varepsilon}_\theta &= \varepsilon g^{\alpha,[1]}_\theta + \frac{\varepsilon^2}{2} g^{\alpha,[2]}_\theta + o(\varepsilon^2) \\
g^{\alpha,\varepsilon}_\varepsilon &= \varepsilon g^{\alpha,[1]}_\varepsilon + \frac{\varepsilon^2}{2} g^{\alpha,[2]}_\varepsilon + o(\varepsilon^2)
\end{align*}
\]

where the coefficients of \(\varepsilon\)-order that is, \(g^{[1]}_r\), \(g^{\alpha,[1]}_\theta\), and \(g^{\alpha,[1]}_\varepsilon\) are given by

\[
\begin{align*}
g^{[1]}_r &= \int_t^T \partial r_\varepsilon^0(u) Y_{t,u} \partial V(x, 0) du \\
g^{\alpha,[1]}_\theta &= \int_t^T \partial \theta_\alpha^0(u) Y_{t,u} \partial V(x, 0) du \\
g^{\alpha,[1]}_\varepsilon &= \int_t^T \theta_\alpha^0(u) \partial \theta_\alpha^0(u) Y_{t,u} \partial V(x, 0) du,
\end{align*}
\]

and the coefficients of \(\varepsilon^2\)-order that is, \(g^{[2]}_r\), \(g^{\alpha,[2]}_\theta\), and \(g^{\alpha,[2]}_\varepsilon\) are given by

\[
\begin{align*}
g^{[2]}_r &= 2 \left( \int_t^T \partial^2 r_\varepsilon^0(u) [D(t; u)] Y_{t,u} du + \int_t^T \partial r_\varepsilon^0(u) Y_{t,u}^1 du \right) \partial^2 V(x, 0) \\
&\quad + \left( \int_t^T \partial r_\varepsilon^0(u) Y_{t,u} du \right) \partial^2 V(x, 0) \\
g^{\alpha,[2]}_\theta &= 2 \left( \int_t^T \partial^2 \theta_\alpha^0(u) [D(t; u)] Y_{t,u} du + \int_t^T \partial \theta_\alpha^0(u) Y_{t,u}^1 du \right) \partial V(x, 0) \\
&\quad + \left( \int_t^T \theta_\alpha^0(u) Y_{t,u} du \right) \partial^2 V(x, 0) \\
g^{\alpha,[2]}_\varepsilon &= 2 \left( \int_t^T \{ \partial \theta_\alpha^0(u) \}^2 + \theta_\alpha^0(u) \partial^2 \theta_\alpha^0(u) \right) [D(t; u)] Y_{t,u} du + \int_t^T \theta_\alpha^0(u) \partial \theta_\alpha^0(u) Y_{t,u}^1 du \partial V(x, 0) \\
&\quad + \left( \int_t^T \theta_\alpha^0(u) \partial \theta_\alpha^0(u) Y_{t,u} du \right) \partial^2 V(x, 0).
\end{align*}
\]

We use the following notations in (29) above;

\[
(\partial \theta_\alpha^0(u))^2 [D(t; u)] Y_{t,u} = \sum_{i=1}^d \sum_{j=1}^d (\partial_i \theta_\alpha^0(u))(\partial_j \theta_\alpha^0(u)) \{D^{(j)}(t; u)\} Y_{t,u}^{(i,\cdot)}
\]

and

\[
\partial^2 \theta_\alpha^0(u) [D(t; u)] Y_{t,u} = \sum_{i=1}^d \sum_{j=1}^d \partial_i \partial_j \theta_\alpha^0(u) \{D^{(j)}(t; u)\} Y_{t,u}^{(i,\cdot)}.
\]

**Proof.** See appendix.
4.3 The Second Order Scheme

Finally, we will explicitly derive an asymptotic expansion of the optimal portfolio up to the $\epsilon$-order. We will also show the third order scheme, that is an asymptotic expansion formula up to the $\epsilon^2$-order in appendix.

We first define $E(1)$ as

$$E(1) \equiv E\left[ (H_{0,t,T})^{\frac{1}{1-\delta}} \times \left( \int_t^T \partial r(X^{\epsilon}_t)Y^\epsilon_{t,u}V(x,\epsilon)du + \sum_{\alpha=1}^r \int_t^T \partial \theta_{\alpha}(X^{\epsilon}_u)Y^\epsilon_{t,u}V(x,\epsilon)dw^\alpha(u) + \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}(X^{\epsilon}_u)\partial \theta_{\alpha}(X^{\epsilon}_u)Y^\epsilon_{t,u}V(x,\epsilon)du \right) \right].$$

Then, we have the following lemma.

**Lemma 5** $E(1)$'s expansion up to the $\epsilon$-order is given by

$$E(1) = e^\left(\frac{\delta}{1-\delta}\right) \epsilon \left( \int_t^T \partial r^{[0]}(u)Y_{t,u}du + \frac{1}{(1-\delta)} \sum_{\alpha=1}^r \int_t^T \theta^{[0]}_{\alpha}(u) \partial \theta^{[0]}_{\alpha}(u)Y_{t,u}du \right) \partial V(x,0) + o(\epsilon).$$

*Proof.* See appendix.

Then, using this result, we have the asymptotic expansion up to the $\epsilon$-order of $E$ defined by the equation (25).

**Lemma 6** $E$'s expansion up to the $\epsilon$-order is given by

$$E = \epsilon \left( \int_t^T \partial r^{[0]}(u)Y_{t,u}du + \frac{1}{(1-\delta)} \sum_{\alpha=1}^r \int_t^T \theta^{[0]}_{\alpha}(u) \partial \theta^{[0]}_{\alpha}(u)Y_{t,u}du \right) \partial V(x,0) + o(\epsilon).$$

*Proof.* See appendix.

Finally, we have the following asymptotic expansion scheme of optimal portfolios for power utilities:

**Theorem 2** Under assumptions [A1] and [A2], an asymptotic expansion up to $\epsilon$-order of the optimal portfolio for the power utility function (22) is given by

$$\pi^*(t)/W = \frac{1}{(1-\delta)} \theta^*(x)\sigma^{-1}(x) + \frac{\delta}{(1-\delta)} \epsilon \left( \int_t^T \partial r^{[0]}(u)Y_{t,u}du + \frac{1}{(1-\delta)} \sum_{\alpha=1}^r \int_t^T \theta^{[0]}_{\alpha}(u) \partial \theta^{[0]}_{\alpha}(u)Y_{t,u}du \right) \partial V(x,0)\sigma^{-1}(x) + o(\epsilon).$$
Proof. Applying lemma 6 to the equation (24) yields the result.

Comparing to the equation (24) which represents the optimal portfolio for power utility functions, we easily see the second term on the right hand side in (32) provides an approximation of the hedging demand that is specific to multiperiod setting, and that appears on the second term on the right hand side in the equation (24).

5 General Case

In this section, we will derive an approximation formula for more general class of utility functions where the Malliavin calculus will be applied. That is, we will consider an asymptotic expansion scheme of the equation (11). First, we remark that the similar argument can be applied as in the power utility functions when \( T \equiv \phi' \) is smooth and

\[
|T^{(n)}(y)| \leq K_n(y^{\alpha_n} + y^{-\beta_n}); \quad 0 < y < \infty,
\]

where \( T^{(n)}(y) \equiv \partial^n T / \partial y^n \), and \( K_n, \alpha_n \) and \( \beta_n \) are positive constants.

Thus, in this section we will concentrate on an asymptotic expansion scheme when \( T \equiv \phi' \) is nonsmooth. We also notice that in practical computation of optimal portfolios for the smooth case we can directly apply the formula (48) in theorem 3 which will be developed for the nonsmooth case. We first consider the functional \( \zeta_{t,u} \) defined in (18) which is equivalent to \( H^0_{0,t,u} \) in the equation (11); That is, \( \zeta_{t,u} = H_{0,t,u} \) where

\[
a_0(X_{tu}) \equiv -\frac{1}{2}|\theta(X_{tu})|^2 - r(X_{tu})
\]

\[
a(X_{tu}) \equiv -\theta(X_{tu})^*.\n\]

We put the following nondegeneracy condition on \( a \):

[A3] For some \( s \in [t,T] \), \( a(X_{su}) \neq 0 \).

Then the Malliavin covariance of \( \zeta_{t,T} \) is given by the formula:

\[
\sigma_{\zeta_{t,T}} = (\zeta_{t,T})^2 \int_t^T |\eta^e(u)|^2 ds,
\]

where the \( r \)-dimensional process \( \eta^e \) is expressed in:

\[
\eta^e(u) = a(X_{tu}) + \sum_{\alpha=0}^r \int_u^T \partial_s a_{\alpha}(X_{su})Y_{t,s}^e(Y_{t,u}^e)\zeta_{s,u}^{-1}V(X_{su}, \epsilon)dw_s^e
\]

with \( a = (a_\alpha)_{\alpha=1}^r \). Take a smooth function \( \varphi : \mathbb{R} \to [0,1] \) such that \( \varphi(x) = 1 \) if \( |x| \leq 1/2 \) and that \( \varphi(x) = 0 \) if \( |x| \geq 1 \). Define \( \xi^e \) by

\[
\xi^e = 4|\zeta_{t,T}^{0}/\zeta_{t,T} - 1|^2 + 4 \left( \int_t^T |a(X_{0u})|^2 du \right)^{-1} \int_t^T |\eta^e(u) - a(X_{0u})|^2 du
\]
and let \( \psi^\varepsilon = \varphi(\xi^\varepsilon) \). Obviously, \( \psi^\varepsilon \in D^\infty \). The exponent of \( \zeta^{0}_{t,T} \) is a Gaussian random variable, therefore \([A3]\) yields the nondegeneracy of \( \zeta^{0}_{t,T} \):

\[
\sigma^{-1}_{\zeta^{0}_{t,T}} \in \cap_{p>1} L^p.
\]

By using this fact and \([A1]\), it is not difficult to show that

\[
\sup_{\varepsilon \in (0,1]} \left\| \psi^\varepsilon \sigma^{-p}_{\zeta^{0}_{t,T}} \right\|_{L^1} < \infty
\]

for any \( p > 1 \), and that

\[
\limsup_{\varepsilon \downarrow 0} \varepsilon^{-n} P [\psi^\varepsilon < 1] < \infty
\]

for any \( n \in \mathbb{N} \). In fact, the first inequality is trivial by the definition of \( \eta^\varepsilon \). The second inequality follows from the \( L^p \)-estimate \( \| \sup_{u \in [t,T]} |X^\varepsilon_u - X^0_u| \|_{L^p} = O(\varepsilon) \) and \([A2]\) with Taylor’s formula.

We will in the sequel assume the boundedness of \( a_{\alpha} (\alpha = 0,1,\ldots,r) \). It will be sufficient for our use. Clearly, Condition \([A2]\) is satisfied, in fact, \( (\zeta^{0}_{t,T})^s \) is integrable for any \( s \in \mathbb{R} \). We will consider the pull-back of \( \zeta^{0}_{t,T} \) by a function \( T \). Under non-degeneracy of \( \zeta^{0}_{t,T} \) the composition \( T(\zeta^{0}_{t,T}) \) with a (roughly speaking) locally integrable function \( T \) is well defined in \( \tilde{D}^{\infty} \) (under truncation, if necessary), and the stochastic expansion of \( T(\zeta^{0}_{t,T}) \) is valid. However, for practical purpose, we need to extend the class of functions \( T \) below. It would be more natural to consider Schwartz distributions on \((0,\infty)\) but we will not pursue it here. It requires global modification of the theory since it is necessary to replace spaces of \( T \) and to prepare another smoothing operator \( A^{-1} \) and estimates. The modification in our discussion is like the finite part of \( x_+^{\lambda} (\lambda > 1) \) in the sense that it removes the difficulty of the lack of the local integrability around zero.

Let

\[
T \text{ is a measurable function such that (33)}
\]

\[
|T(y)| \leq K (y^\alpha + y^{-\beta}) \text{ for some } K > 0, \alpha > 0 \text{ and } \beta \in (0,1).
\]

We will consider utility functions of which \( \varphi' \) belong to class of \( T \). The function \( T \) may not be a Schwartz distribution but the composite function \( T(\zeta^{0}_{t,T}) \) is of course well defined in \( \tilde{D}^{\infty} \):

\[
\psi^\varepsilon T(\zeta^{0}_{t,T}) \text{ in } \tilde{D}^{\infty}.
\]

(34)

It should be noted that \( (\zeta^{0}_{t,T}) \) is non-degenerate under truncation by \( \psi^\varepsilon \). Let \( \hat{g}^{\alpha,\varepsilon} \) be a family of Wiener functionals admitting a stochastic expansion:

\[
\hat{g}^{\alpha,\varepsilon} \sim \sum_{j=0}^{\infty} \frac{\varepsilon^j}{j!} \hat{g}^{\alpha,[j]}
\]
in $D^\infty$ as $\epsilon \downarrow 0$. Then one obtains the stochastic expansion:

$$\hat{g}^{\alpha,\epsilon} T(\zeta_{t,T}) \sim \sum_{j=0}^{\infty} \epsilon^j \tilde{\Phi}^\alpha_j[\hat{g}]$$  \hspace{1cm} \text{(35)}$$

in $\tilde{D}^{-\infty}$ as $\epsilon \downarrow 0$. Here the coefficients $\tilde{\Phi}^\alpha_j[\hat{g}] \in \tilde{D}^{-\infty}$ are determined by the formal Taylor expansion of the left-hand side after removing $\psi^\epsilon$. Expectation of (35) yields the ordinary asymptotic expansion:

$$< \hat{g}^{\alpha,\epsilon} T(\zeta_{t,T}), 1 > \sim \sum_{j=0}^{\infty} \epsilon^j < \tilde{\Phi}^\alpha_j[\hat{g}], 1 > \sim \sum_{j=0}^{\infty} \epsilon^j \int_{-\infty}^{\infty} T(z)p_j(z; \hat{g})dz,$$

where $< \cdot, \cdot >$ denotes the generalized expectation, and $p_j(z; \hat{g})$ are integrable smooth functions, which can be described as the transform of the derivatives of the density of $\zeta_{t,T}$ multiplied by the conditional expectation of certain smooth functionals given $\zeta_{t,T}$. On the other hand, if $T \in S(\mathbb{R})$, that is $T$ belongs to the Schwartz space of rapidly decreasing $C^\infty$ functions on $\mathbb{R}$, then with no problem we obtain

$$\hat{g}^{\alpha,\epsilon} T(\zeta_{t,T}) \sim \sum_{j=0}^{\infty} \epsilon^j \Phi^\alpha_j[\hat{g}]$$  \hspace{1cm} \text{(37)}$$

and hence

$$< \hat{g}^{\alpha,\epsilon} T(\zeta_{t,T}), 1 > \sim \sum_{j=0}^{\infty} \epsilon^j \int_{-\infty}^{\infty} T(z)p_j(z; \hat{g})dz$$  \hspace{1cm} \text{(38)}$$

for some smooth functions $\tilde{p}_j(z; \hat{g})$. Clearly, the expansion (36) coincides with the expansion (38) for $T \in S(\mathbb{R})$, and hence $p_j(z; \hat{g}) = \tilde{p}_j(z; \hat{g})$.

Summarizing,

$$< \hat{g}^{\alpha,\epsilon} T(\zeta_{t,T}), 1 > \sim \sum_{j=0}^{\infty} \epsilon^j \int_{-\infty}^{\infty} T(z)p_j(z; \hat{g})dz$$  \hspace{1cm} \text{(39)}$$

as $\epsilon \downarrow 0$, for measurable functions $T$ admitting the representation $T(y) = \hat{T}(y^\gamma)$, where $p_j(z; \hat{g})$ are determined as follows. By the formal Taylor expansion

$$\left( \sum_{j=0}^{\infty} \frac{\epsilon^j}{j!} \hat{g}^{\alpha,[j]} \right) T(\zeta_{t,T}) + \sum_{j=1}^{\infty} \frac{\epsilon^j}{j!} \zeta_{t,T}^{[j]} = \sum_{j=0}^{\infty} \epsilon^j \Phi^\alpha_j[\hat{g}],$$

one has an expression of $\Phi^\alpha_j[\hat{g}]$:

$$\Phi^\alpha_j[\hat{g}] = \sum_{k=0}^{j} J_k \partial^k T(\zeta_{t,T}),$$
for some functionals $J_k$, $k = 0, \ldots, j$. Then $p_j(z; \hat{g})$ is given by

$$
p_j(z; \hat{g}) = \sum_{k=0}^{j} (-\partial_z)^k \left\{ E[J_k|\zeta_{t,T}^0 = z] p^{S_{t,T}}(z) \right\},
$$

where $p^{S_{t,T}}(z)$ denotes the density function of $\zeta_{t,T}^0$.

Next, we will explicitly derive the asymptotic expansion for the general case based on the previous validity argument. We first note that we are able to express $\mathcal{Y}$ in terms of $W$ and $x$ through a function $\mathcal{Y} = \mathcal{Y}(W, x)$ because $W = \mathbb{E}[H_{0,t,T}I(\mathcal{Y}H_{0,t,T})]$ and $I(\cdot)$ is strictly decreasing. Hereafter, $\mathcal{Y}$ is regarded as a constant since we will derive a general formula given $W$, $x$ and a function $\mathcal{Y}(\cdot, \cdot)$.

We start with the stochastic expansion of $H_{0,t,T}$ around $\epsilon = 0$:

**Lemma 7** The asymptotic expansion of $H_{0,t,T}$ up to $\epsilon^2$-order is given by

$$
H_{0,t,T} = H_{0,t,T}^{[0]} + \epsilon H_{0,t,T}^{[1]} + \frac{\epsilon^2}{2} H_{0,t,T}^{[2]} + o(\epsilon^2),
$$

where

$$
\begin{align*}
H_{0,t,T}^{[0]} &= \exp \left( -\int_t^T \theta(u)\hat{g}(u)\ast du(u) - \frac{1}{2} \int_t^T |\theta(u)|^2 du - \int_t^T r^{[0]}(u)du \right), \\
H_{0,t,T}^{[1]} &= R_1 + \Theta_{21} + \Theta_1, \\
H_{0,t,T}^{[2]} &= (H_{0,t,T}^{[1]})^2 + R_2 + \Theta_{22} + \Theta_2.
\end{align*}
$$
Here we define $R_1$, $\Theta_{21}$, $\Theta_1$, $R_2$, $\Theta_{22}$ and $\Theta_2$ as follows.

\[
\begin{align*}
R_1 & \equiv - \int_t^T \partial r^{[0]}(u) D(t; u) du \\
\Theta_{21} & \equiv - \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}^{[0]}(u) \partial \theta_{\alpha}^{[0]}(u) D(t; u) du \\
\Theta_1 & \equiv - \sum_{\alpha=1}^r \int_t^T \partial \theta_{\alpha}^{[0]}(u) D(t; u) du^\alpha(u) \\
R_2 & \equiv - \int_t^T \{ \partial^2 r^{[0]}(u) [D(t; u), D(t; u)] + \partial r^{[0]}(u) E(t; u) \} du \\
\Theta_{22} & \equiv - \sum_{\alpha=1}^r \int_t^T \{ \partial \theta_{\alpha}(u) D(t; u) \}^2 du - \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}^{[0]}(u) \{ \partial^2 \theta_{\alpha}^{[0]}(u) [D(t; u), D(t; u)] + \partial \theta_{\alpha}(u) E(t; u) \} du \\
\Theta_2 & \equiv - \int_t^T \{ \partial^2 \theta_{\alpha}^{[0]}(u) [D(t; u), D(t; u)] + \partial \theta_{\alpha}^{[0]}(u) E(t; u) \} du \\
\end{align*}
\]

Proof. Set $\zeta_{t,u} \equiv H_{0,t,T}$, and apply (19) in lemma 2.

Next, we will explicitly derive the expansions of $E(2)$ and $E(3)$ up to the $\epsilon$-order. We provide the following lemma for the expansion of $E(2)$.

**Lemma 8** The asymptotic expansion of $E(2)$ defined by (40) up to the $\epsilon$-order is given by

\[
E(2) = e^{-\int_t^T r^{[0]}(u) du} \left( \int_{-\infty}^{\infty} \phi'(\xi_{t,T,Y} e^z) p(z) dz \right) - \epsilon \int_t^T r^{[0]}(u) du \left( \int_{-\infty}^{\infty} (c_{22} z^2 + c_{21} z + c_{20}) p(z) dz \right) + o(\epsilon),
\]

where

\[
\begin{align*}
\xi_{t,T,Y}^{(1)} & \equiv Y e^{-\int_t^T r^{[0]}(u) du} e^{\frac{1}{2} \int_t^T (\theta^{[0]}(u))^2 du}, \\
\xi_{t,T,Y}^{(2)} & \equiv Y e^{-\int_t^T r^{[0]}(u) du} e^{\frac{3}{2} \int_t^T (\theta^{[0]}(u))^2 du},
\end{align*}
\]

and

\[
p(z) \equiv \frac{1}{\sqrt{2\pi} \Sigma z} e^{-\frac{z^2}{2 \Sigma z}}, \quad \Sigma z \equiv \int_t^T |\theta^{[0]}(u)|^2 du.
\]

Moreover, $c_{i0}$, $c_{i1}$ and $c_{i2}$ for $i = 1, 2$ are defined as follows;

\[
\begin{align*}
c_{i0} & \equiv i \sum_{\alpha=1}^r \int_t^T ( \theta_{\alpha}^{[0]} \partial \theta_{\alpha}^{[0]} D_i(t; u) du - \int_t^T \partial r^{[0]}(u) \bar{D}_i(t; u) du - \sum_{\alpha=1}^r \int_t^T \partial \theta_{\alpha}^{[0]} \partial \theta_{\alpha}^{[0]} D_i(t; u) du \\
& \quad + \frac{1}{2 \Sigma z} \left\{ \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}(u) \partial \theta_{\alpha}(u) Y_{t,u} \left( \int_{t}^u Y_{t,s}^{-1} \sum_{\alpha=1}^r \partial \epsilon V s \theta_{\alpha}^{[0]}(s) ds \right) du \right\} \\
c_{i1} & \equiv \frac{1}{2 \Sigma z} \left\{ \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}(u) \partial \theta_{\alpha}(u) Y_{t,u} \left( \int_{t}^u Y_{t,s}^{-1} \partial \epsilon V s \theta_{\alpha}^{[0]}(s) ds \right) du + \frac{1}{2 \Sigma z} \int_t^T \partial r^{[0]}(u) Y_{t,u} \int_{t}^u Y_{t,s}^{-1} \partial \epsilon V s \theta_{\alpha}^{[0]}(s) ds du \right\} \\
& \quad + \frac{1}{2 \Sigma z} \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}(u) \partial \theta_{\alpha}(u) Y_{t,u} \left( \int_{t}^u Y_{t,s}^{-1} \partial \epsilon V s \theta_{\alpha}^{[0]}(s) ds \right) du \\
c_{i2} & \equiv - \frac{1}{2 \Sigma z} \left\{ \sum_{\alpha=1}^r \int_t^T \theta_{\alpha}(u) \partial \theta_{\alpha}(u) Y_{t,u} \left( \int_{t}^u Y_{t,s}^{-1} \sum_{\alpha=1}^r \partial \epsilon V s \theta_{\alpha}^{[0]}(s) ds \right) du \right\},
\end{align*}
\]
where
\[ \tilde{D}_t(t; u) = Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_t V_s ds - i Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_t \theta^{[0]}(s) ds. \] (46)

Proof. See appendix.

In the similar manner, we obtain the expansion of \( E(3) \).

Lemma 9 The asymptotic expansion of \( E(3) \) defined by (41) up to the \( \epsilon \)-order is given by
\[
E(3) = \epsilon e^{- \int_0^T r^{[0]}(u) du} \left[ \left( \int_{-\infty}^{\infty} \phi'(\xi^{(1)}_{t,T,Y} e^z) p(z) dz \right) \times \left( \int_t^T \partial r^{[0]}(u) Y_{t,u} du + \sum_{\alpha=1}^r \int_t^T \partial_{\alpha}^{[0]}(u) \partial_{\alpha}^{[0]}(u) Y_{t,u} du \right) \right. \\
+ \left. \left( \int_{-\infty}^{\infty} \phi'(\xi^{(1)}_{t,T,Y} e^z)(c_{31} z + c_{30}) p(z) dz \right) \right] \partial_e V(x, 0) + o(\epsilon),
\]
where \( c_{30} \) and \( c_{31} \) are constants which are defined as follows:
\[
\begin{align*}
& c_{30} = - \sum_{\alpha=1}^r \int_t^T \partial_{\alpha}^{[0]}(u) \partial_{\alpha}^{[0]}(u) Y_{t,u} du \\
& c_{31} = - \sum_z c_{30}.
\end{align*}
\] (47)

Proof. See appendix.

Finally, we obtain the following theorem:

Theorem 3 Suppose that a utility function satisfies the conditions (4) and that \( \phi' \) belongs to class of (33). Then, under \([A1], [A2] \) and \([A3] \) the asymptotic expansion of the optimal portfolio for investment is given by
\[
\tilde{\pi}^*(t; x) = \left\{ \left[ W - \epsilon e^{- \int_0^T r^{[0]}(u) du} \left( \int_{-\infty}^{\infty} \phi'(\xi^{(1)}_{t,T,Y} e^z) p(z) dz \right) \right] \right. \\
- \epsilon e^{- \int_0^T r^{[0]}(u) du} \left\{ \left( \int_{-\infty}^{\infty} (c_{12} z^2 + c_{11} z + c_{10}) \phi'(\xi^{(1)}_{t,T,Y} e^z) p(z) dz \right) \right. \\
- \mathcal{Y} e^{- \int_0^T r^{[0]}(u) du} \left\{ \left( \int_{-\infty}^{\infty} \phi'(\xi^{(2)}_{t,T,Y} e^z) \partial_z \left\{ \left( c_{22} z^2 + c_{21} z + c_{20} \right) p(z) \right\} dz \right) \right. \\
- \epsilon e^{- \int_0^T r^{[0]}(u) du} \left[ \left( \int_{-\infty}^{\infty} \phi'(\xi^{(1)}_{t,T,Y} e^z) p(z) dz \right) \times \\
\left( \int_t^T \partial r^{[0]}(u) Y_{t,u} du + \sum_{\alpha=1}^r \int_t^T \partial_{\alpha}^{[0]}(u) \partial_{\alpha}^{[0]}(u) Y_{t,u} du \right) \right. \\
+ \left. \left( \int_{-\infty}^{\infty} \phi'(\xi^{(1)}_{t,T,Y} e^z)(c_{31} z + c_{30}) p(z) dz \right) \right] \partial_e V(x, 0) + o(\epsilon),
\]
where \( \xi^{(i)}_{t,T,Y}, i = 1, 2 \) are defined by (43), \( p(z) \) is defined by (44), \( c_{i0}, c_{i1} \) and \( c_{i2} \) for \( i = 1, 2 \) are defined by (45) and (46), and \( c_{30} \) and \( c_{31} \) are defined by (47).
We notice that the term multiplied by \( \theta^*(x) \) approximates the mean-variance component of the optimal portfolio while the term multiplied by \( \partial_1 V(x,0) \) provides an approximation of the hedging demand.

**Remark 1** In the above theorems, we used the boundedness assumption of \( \theta \). On the other hand, it is possible to relax such a boundedness condition due to the following localizing arguments. Let us consider the computation of the expectation \( E[\tilde{g}^{\alpha,\epsilon}T(\tilde{\zeta}_{t,T})] \) discussed before. We start with \( \theta \) which is smooth but not necessarily bounded. Given a large number \( M \) such that \( \sup_{t\in[0,T]}|X_p^t|<M \), we choose smooth modifications \( \tilde{\theta} \) so that \( \tilde{\theta} \) is bounded, and that \( \tilde{\theta} = \theta \) over the region \( \{x: |x|<M\} \). We also define \( \tilde{\zeta}_{t,T} \) with those modifications. Condition [A3] for the modified functions is the same as that for the original functions. So under [A3] for the original functions, we already have the asymptotic expansion of \( E[\tilde{g}^{\alpha,\epsilon}T(\tilde{\zeta}_{t,T})] \). On the other hand,

\[
\left| E[\tilde{g}^{\alpha,\epsilon}T(\tilde{\zeta}_{t,T})] - E[\hat{g}^{\alpha,\epsilon}T(\hat{\zeta}_{t,T})] \right| = E \left| \tilde{g}^{\alpha,\epsilon}T(\tilde{\zeta}_{t,T}) - \hat{g}^{\alpha,\epsilon}T(\hat{\zeta}_{t,T}) \right| _{\{\sup_{t\in[0,T]}|X_p^t|>M\}} \\
\leq \sup_{\epsilon} \|\tilde{g}^{\alpha,\epsilon}\|_{p_1} \sup_{\epsilon} \left\{ \|T(\tilde{\zeta}_{t,T})\|_{p_2} + \|T(\hat{\zeta}_{t,T})\|_{p_3} \right\} P \left[ \sup_{t\in[0,T]}|X_p^t|>M \right]^{1/p_3},
\]

where \( p_1, p_2, p_3 \in (1,\infty) \) (\( p_1^{-1} + p_2^{-1} + p_3^{-1} = 1 \)). Thus, under the finiteness of the second factor on the right-hand side, we will obtain an asymptotic expansion of \( E[\hat{g}^{\alpha,\epsilon}T(\hat{\zeta}_{t,T})] \).

### 6 A Numerical Example

In this section, we will illustrate our method through a numerical example. In particular, following theorem 2, we will provide analytic approximations of optimal portfolios for an example investigated by Detemple et al.(2000) who relies on naive Monte Carlo simulations as numerical technique. First, we divide the optimal portfolio for a power utility function in the equation (24) into the mean variance, the interest rate hedge (IR-hedge) and the market price of risk hedge (MPR-hedge) components defined as follows:

\[
\text{mean variance} \equiv \frac{1}{(1-\delta)} \theta(x)^* \sigma^{-1}(x) \\
\text{IR-hedge} \equiv \frac{\delta}{(1-\delta)} \frac{1}{E[H_{0,t,T}^{-\frac{\alpha}{1-\delta}}]} \int_t^T \partial_1 r(X_u^\epsilon) Y_{t,u}^\epsilon du \sigma^{-1}(x) \\
\text{MPR-hedge} \equiv \frac{\delta}{(1-\delta)} \frac{1}{E[H_{0,t,T}^{-\frac{\alpha}{1-\delta}}]} \int_t^T \partial_\alpha \theta(X_u^\epsilon) Y_{t,u}^\epsilon du \alpha(u)
\]
In this example, we suppose that mean variance \( \equiv \) asymptotic expansion in theorem 2 are given as follows:

\[
\theta^\epsilon(x) = \epsilon \left( \prod_{\alpha=1}^{\mathcal{E}} \int_\nu^\mathcal{T} \theta_\alpha(X_{u}^\epsilon) \partial \theta_\alpha(X_{u}^\epsilon) Y_{t,u}^\epsilon du \right) \int V(x, \epsilon) \sigma^{-1}(x).
\]

We remark that hedging demand is further divided into IR-hedge and MPR-hedge components above. Next, the corresponding components for the asymptotic expansion in theorem 2 are given as follows:

mean variance \( \equiv \frac{1}{1-\delta} \theta^\epsilon(x) \sigma^{-1}(x) \)

IR-hedge \( \equiv \epsilon \frac{\delta}{(1-\delta)} \left( \int_\nu^\mathcal{T} \partial r[0](u) Y_{t,u}^\epsilon du \right) \partial \epsilon V(x, 0) \sigma^{-1}(x) \)

MPR-hedge \( \equiv \epsilon \frac{\delta}{(1-\delta)^2} \left( \sum_{\alpha=1}^{\mathcal{E}} \int_\nu^\mathcal{T} \partial \theta[0](u) \partial \theta[0](u) Y_{t,u}^\epsilon du \right) \partial \epsilon V(x, 0) \sigma^{-1}(x) \).

In this example, we suppose that \( d = 2 \), that is \( X_{u}^\epsilon = (X_{u}^\epsilon(1), X_{u}^\epsilon(2)) \) and that they satisfy the following stochastic differential equations:

\[
\begin{align*}
\{ & dX_{u}^\epsilon(1) = \kappa_1(X_{u}^\epsilon(1) - X_{u}^\epsilon(1)) du - \epsilon (X_{u}^\epsilon(1))^{1/2} dw_u; \quad X_{0}^\epsilon(1) = r_0 \\
& dX_{u}^\epsilon(2) = \kappa_2(X_{u}^\epsilon(2) - X_{u}^\epsilon(2)) du + \epsilon \sigma_2 dw_u; \quad X_{0}^\epsilon(2) = \theta_0
\end{align*}
\]

where \( w \) denotes one dimensional Brownian motion(\( r = 1 \)). \(^1\) We also suppose that there exist one risky asset and a locally riskless asset, and that \( \theta_u = X_{u}^\epsilon(2) \) and \( r_u \) is a smooth modification of \( \min\{X_{u}^\epsilon(1), M\} \) where \( M \) is a positive large number. Then, the dynamics of both assets are described by

\[
\begin{align*}
\{ & dS_{u}^\epsilon = S_{u}^\epsilon(X_{u}^\epsilon(1) + \sigma X_{u}^\epsilon(2)) du + S_{u}^\epsilon \sigma dw_u, \quad S_{0}^\epsilon(0) = s \\
& dS_{0u}^\epsilon = S_{0u}^\epsilon r(X_{u}^\epsilon(1)) du, \quad S_{0}^\epsilon(0) = 1
\end{align*}
\]

In Appendix, we will discuss the validity of the asymptotic expansions for this setting in detail. Further, we set the values of the parameters for \( X_{u}^\epsilon \) following Detemple et al.(2000), which were obtained by statistical estimation; \( \kappa_1 = 0.0824, r_0 = \bar{\bar{X}}^\epsilon(1) = 0.06, \epsilon = 0.03637, \kappa_2 = 0.6950, \bar{\bar{X}}^\epsilon(2) = 0.0871, \sigma_2 = 0.21/0.03637, \theta_0 = 0.1, \sigma = 0.2. \)

For comparison we also compute each component of the optimal portfolios by using Monte Carlo simulations based on the Euler-Maruyama approximation; the discretized time step \( \Delta t \) is 1/365 and the number of trials is 100,000 in each Monte Carlo simulation.

The percentage-shares in total wealth of Mean variance, MPR-hedge component, IR-hedge component, and the total demand which are sum of those

\(^1\) The volatility function of \( X_{u}^\epsilon(1) \) is not smooth at the origin and we need to use a smoothed version of the square root process at the origin. However, we can show that the smoothing does not make significant differences and the effects are negligible in the small disturbance asymptotic theory.
three components are listed in table 1-4; the results for the asymptotic expansion are listed in tables 1 and 2 while the results for the Monte Carlo simulation are listed in tables 3 and 4. In addition, tables 1 and 3 show the results for investment horizons $T = 1, 2, 3, 4, 5$ when the Arrow-Pratt measure of relative risk aversion $R(\equiv 1 - \delta)$ is fixed at 2, and tables 2 and 4 show the results for $R = 0.5, 1, 1.5, 4, 5$ when $T = 1$. We remark that total demand means the demand for the risky asset and hence it may not be 100% because the remaining shares (100% - total demand) are invested into the riskless asset. We also note that it may exceeds 100% since selling (borrowing) riskless asset is admitted. We can observe that the results of asymptotic expansion and of Monte carlo simulation are so close for IR-hedge while there is some difference for MPR-hedge, but the difference is small relative to the total demand. We also notice that the second order scheme gives substantial improvement comparing with the first order scheme which is equivalent to the case that we ignore the hedging components. (Note that $O(1)$ for MPR-hedge and IR-hedge components are zero.) Thus, we have confirmed that our method is not only computational efficient, but also gives sufficient approximations to the evaluation of the optimal portfolios.

References


7 Appendix

7.1 Proofs of Lemmas

(Proof of lemma 1)

Using (13), (14) and solutions of the set of stochastic differential equations
Moreover, applying the expansion (19) in lemma 2, we can obtain

\[ g^{\alpha,0} = 0 \quad (\alpha = 0, 1, ..., r) \tag{49} \]

since \( V(x, 0) \equiv 0 \) from [A1]. Then, we compute explicitly \( g^{\alpha,[j]}, j = 1, 2 \), and by tedious routine work, we obtain the result.

**Proof of lemma 3**

We first see that

\[ g^{\alpha,0} = 0 \quad (\alpha = 0, 1, ..., r) \]

since \( V(x, 0) \equiv 0 \) from [A1]. Then, we compute explicitly \( g^{\alpha,[j]}, j = 1, 2 \), and by tedious routine work, we obtain the result.

**Proof of lemma 4**

Replacing \( f(\cdot) \) in the equation (20) by \( r(\cdot), \theta(\cdot), \frac{1}{2} \theta^2(\cdot) \) and applying the result in lemma 3, we obtain the expansions of \( g_\alpha^r, g_\theta^r, \) and \( g_\theta^{\alpha,\epsilon} \).

**Proof of lemma 5**

Applying the expansions (27), (28), and (29) in lemma 4 directly, we obtain

\[
\left( \int_t^T \partial r(X_u^\epsilon) Y_{t,u}^\epsilon V(x, \epsilon) du + \sum_{\alpha=1}^r \int_t^T \partial \theta(\alpha) X_u^\epsilon Y_{t,u}^\epsilon V(x, \epsilon) du \right) \\
+ \sum_{\alpha=1}^r \int_t^T \theta(\alpha) X_u^\epsilon \partial \theta(\alpha) X_u^\epsilon Y_{t,u}^\epsilon V(x, \epsilon) du \\
= \epsilon \left( \int_t^T \partial r^{0} (\cdot) Y_{t,u}^{0} du \right) + \sum_{\alpha=1}^r \int_t^T \partial \theta^{0} (\alpha) Y_{t,u}^{0} du + \epsilon \sum_{\alpha=1}^r \int_t^T \theta^{0} (\alpha) \theta^{0} (\alpha) Y_{t,u}^{0} du \\
+ o(\epsilon).
\]

Moreover, applying the expansion (19) in lemma 2, we can obtain

\[
\zeta_{t,u}^{\epsilon} \equiv \left( H_{0,t,T} \right)^{\epsilon,\epsilon} = \\
e^{-\frac{1}{2}(\epsilon - \delta)^2} \int_t^T r^{0} (\cdot) du \frac{\delta}{2(1-\delta)^2} \int_t^T \theta^{0} (\cdot) du \\
e^{-\frac{1}{2}(\epsilon - \delta)^2} \int_t^T \theta^{0} (\cdot) du \times \\
\left( 1 + \epsilon \frac{\delta}{1-\delta} \int_t^T \partial r^{0} (\cdot) D(t; u) du + \epsilon \frac{\delta}{1-\delta} \sum_{\alpha=1}^r \int_t^T \partial \theta^{0} (\alpha) D(t; u) du \right) \\
+ \epsilon \left( \frac{\delta}{1-\delta} \right) \sum_{\alpha=1}^r \int_t^T \theta^{0} (\alpha) \theta^{0} (\alpha) D(t; u) du + o(\epsilon).
\]

Then, by change of the measure technique with

\[
\hat{P}(A) \equiv \mathbb{E} \left[ 1_A \exp \left( -\frac{1}{2} \frac{\epsilon - \delta}{1-\delta} \int_t^T \theta^{0} (\cdot) du \right) \right] ; \ A \in \mathcal{F}_T
\]
simple calculation yields the result.

(Proof of lemma 6)

Using (19) again, we can obtain the expansion:

\[
E \left[ \left( H_{0,t,T} \right)^{1 - \frac{\delta}{2}} \right] = e^{\frac{\delta}{1 - \delta} \int_t^T \frac{\partial}{\partial u} \left( H_{0,0,t,T} \right) \left( 1 + \frac{\delta}{2} \int_t^T \left( H_{0,0,t,T} \right)^2 \right) du} \times
\]

\[\left( 1 + e^{\frac{\delta}{1 - \delta} \int_t^T \partial \frac{r_{0,0}(u)}{\partial u} \dot{D}_1(t; u) du} + e^{\frac{\delta}{1 - \delta} \sum_{\alpha=1}^{r} \int_t^T \frac{\partial}{\partial \alpha} \frac{r_{0,0}(u)}{\partial \alpha} \dot{D}_1(t; u) du} + o(\epsilon). \]

where

\[
\dot{D}_1(t; u) \equiv Y_{0,t} \int_t^u Y_{0,t,s}^{-1} \left( \partial V_{0,0}(s) ds + \left( \frac{\delta}{1 - \delta} \right) \partial V_{0,0}(s) \theta_{0,0}(s) ds \right). \]

Then, gathering (30) in lemma 5 and (50), we obtain the result.

(Proof of lemma 8)

Note first that the asymptotic expansion of \( E(2) \) is expressed as

\[
E(2) = E[H_{0,t,T} \phi'(\mathcal{Y} H_{0,t,T})]
\]

\[+ \epsilon E[H_{0,t,T}^2 \phi'(\mathcal{Y} H_{0,t,T})] + \epsilon \mathcal{Y} E[(H_{0,t,T})^2 H_{0,t,T} \partial \phi'(\mathcal{Y} H_{0,t,T})] + o(\epsilon). \]

Then, by using lemma 7, we can easily obtain the expression for the first term of (51).

\[
E[H_{0,t,T} \phi'(\mathcal{Y} H_{0,t,T})] = e^{-\int_t^T r_{0,0}(u) du} E(1)[\phi' \left( \xi_{1,t,T} e^{-\int_t^T \theta_{0,0}(u) du} \right)]
\]

\[
= e^{-\int_t^T r_{0,0}(u) du} \left( \int_{-\infty}^{\infty} \phi' \left( \xi_{1,t,T} e^{-\int_t^T \theta_{0,0}(u) du} \right) p(z) dz \right)
\]

where

\[
\xi_{1,t,T} = \mathcal{Y} e^{-\int_t^T r_{0,0}(u) du} e^{\frac{1}{2} \int_t^T (\theta_{0,0}(u))^2 du},
\]

\[z = -\int_t^T \theta_{0,0}(u) du,
\]

\[p(z) = \frac{1}{\sqrt{2\pi \Sigma_z}} e^{-\frac{z^2}{2\Sigma_z}}, \quad \Sigma_z = \int_t^T (\theta_{0,0}(u))^2 du.
\]

Moreover, \( E^{(1)}[\cdot] \) denotes the expectation operator under

\[
P_1(A) \equiv E \left[ 1_A \exp \left( -\int_t^T \theta_{0,0}(u) dw(u) - \frac{1}{2} \int_t^T (\theta_{0,0}(u))^2 du \right) \right]
\]

26
for all $A \in \mathcal{F}_T$, and $w_1(u) = w(u) + \int_t^u \theta^{[0]}(s)ds$ denotes the standard Brownian motion under $P_1$.

We can also obtain expressions for the second and third terms of (51) after tedious calculation with lemma 7 as follows:

$$
\epsilon E[H_{0,t,T}^{[0]} | H_{0,t,T}^{[1]} \phi'(YH_{0,t,T}^{[0]})]
= e^{-\epsilon} \int_t^T r^{[0]}(u)du E[1] \left[ (R_1 + \Theta_{21} + \Theta_1) \phi'(YH_{0,t,T}^{[0]}) \right]
= e^{-\epsilon} \int_t^T r^{[0]}(u)du E[1] \left[ \phi'(YH_{0,t,T}^{[0]}) E[1] \left[ (R_1 + \Theta_{21} + \Theta_1) | z = - \int_t^T \theta^{[0]}(u)dw_1(u) \right] \right]
= e^{-\epsilon} \int_t^T r^{[0]}(u)du \left( \int_{-\infty}^{\infty} (c_{12}z^2 + c_{11}z + c_{10}) \phi'(\xi_{t,T,Y}^{[1]} z^2 + z^2) p(z) dz \right)
$$

where $c_{i2}, c_{i1}, c_{i0}$ for $i = 1, 2$ are some constants which are explicitly given later. Moreover, we use the notations:

$$
\xi_{t,T,Y}^{[2]} = \sqrt{2} \int_t^T r^{[0]}(u)du e^{\frac{z}{\sqrt{2} \int_t^T r^{[0]}(u)du}}
$$

$$
z = - \int_t^T \theta^{[0]}(u)dw_2(u)
$$

$$
p(z) = \frac{1}{\sqrt{2\pi} \sum_{r} e^{-\frac{r^2}{2 \sum_{r}}}, \sum_{r} = \int_t^T |\theta^{[0]}(u)|^2 du.}
$$

Further, $E[2] \cdot$ denotes the expectation operator under

$$
P_2(A) \equiv E \left[ 1_A \exp \left( -2 \int_t^T \theta^{[0]}(u)^* dw(u) - 2 \int_t^T |\theta^{[0]}(u)|^2 du \right) \right]
$$

for all $A \in \mathcal{F}_T$, and $w_2(u) = w(u) + 2 \int_t^u \theta^{[0]}(s)ds$ denotes the standard Brownian motion under $P_2$.

Finally, in order to obtain $c_{i,j}$ for $i = 1, 2$ and $j = 0, 1, 2$ explicitly, we will evaluate $E[[R_1 + \Theta_{21} + \Theta_1] | z = - \int_t^T \theta^{[0]}(u)dw_1(u)]$ for $i = 1, 2$:

$$
E[[R_1] | z = - \int_t^T \theta^{[0]}(u)dw_1(u)] = i \sum_{\alpha=1}^{r} \int_t^T \theta^{[0]}_\alpha \theta^{[0]}_\alpha \hat{D}_i(t; u)du
$$

$$
- \left( \frac{1}{\sum_{r}} z^2 - \frac{1}{\sum_{r}} \right) \left\{ \sum_{\alpha=1}^{r} \int_t^T \theta^{[0]}_\alpha \theta^{[0]}_\alpha Y_{i,u}^{[0]} \left( \int_t^u Y_{i,u}^{[0]} \sum_{\alpha=1}^{r} \hat{V}_s \theta^{[0]}(s) ds \right) du \right\}
$$

27
\[ \frac{1}{\Sigma z} \sum_{\alpha=1}^{r} \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} V_0 ds du \]

\[ \mathbf{E}^{(i)} \left[ R_1 | z = - \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} V_0 | d\omega_i (u) \right] = \]

\[ - \int_t^T \partial r^0 (u) \tilde{D}_1 (t; u) du + \frac{1}{\Sigma z} \sum_{\alpha=1}^{r} \int_t^T \partial r^0 (u) Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} \theta^0 (s) ds du \]

\[ \mathbf{E}^{(i)} \left[ \Theta_{21} | z = - \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} \theta^0 (s) ds du \right] = \]

\[ - \sum_{\alpha=1}^{r} \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} \tilde{D}_1 (t; u) du + \frac{1}{\Sigma z} \sum_{\alpha=1}^{r} \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} \theta^0 (s) ds du \]

where

\[ \tilde{D}_1 (t; u) \equiv Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} V_0 ds - i Y_{t,u} \int_t^u Y_{t,s}^{-1} \partial_{V_s} \theta^0 (s) ds. \]

Hence, we obtain the expressions of \( c_{i2}, c_{i1}, c_{i0} \) for \( i = 1, 2 \) by (45) and (46).

**Proof of lemma 9**

Using the assumption [A1]: \( V(\cdot, 0) \equiv 0 \), and evaluation of conditional expectation of a Gaussian random variable;

\[ \mathbf{E}^{(1)} \left[ \sum_{\alpha=1}^{r} \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} d\omega^\alpha (u) | z = - \int_t^T \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} d\omega_1 (u) \right] = c_{31} z + c_{30}, \]

we obtain the result.

### 7.2 The Third Order Scheme for a Power Utility Function

We show the result of the third order scheme, the asymptotic expansion up to the \( \epsilon^2 \)-order of the optimal portfolio for a power utility function.

**[The third order scheme]**

\[ \pi^* (t) = \frac{W}{(1 - \delta)} [\theta^*(x) + \delta(\epsilon A + \epsilon^2 B - \epsilon^2 AC)] | \sigma^{-1} (x) + o(\epsilon^2) \]

where

\[ A \equiv \left( \int_t^T \partial r^0 \frac{\partial \theta^0}{\partial \alpha} \frac{\partial \theta^0}{\partial \alpha} Y_{t,u} du + \frac{1}{(1 - \delta)} \sum_{\alpha=1}^{r} \int_t^T \frac{\partial \theta^0}{\partial \alpha} (u) \partial \theta^0 (u) Y_{t,u} du \right) \partial_{V} V (x, 0), \]

\[ C \equiv \left( \frac{\delta}{1 - \delta} \right) \int_t^T \partial r^0 (u) \partial \tilde{D}_1 (t; u) du + \frac{\delta}{(1 - \delta)^2} \sum_{\alpha=1}^{r} \int_t^T \frac{\partial \theta^0}{\partial \alpha} (u) \partial \theta^0 (u) \tilde{D}_1 (t; u) du, \]

and \( B \) is the sum of the following terms:

1. \( \left( \frac{\delta}{1 - \delta} \right) \int_t^T \partial r^0 (u) \tilde{D}_1 (t; u) du \left\{ \int_t^T \partial r^0 (u) Y_{t,u} du \right\} \partial_{V} V (x, 0) \)
2. 
\[
\left(\frac{\delta}{1-\delta}\right)^2 \left\{ \int_t^T \partial r[0](u) \dot{D}_1(t; u) du \right\} \left\{ \sum_{\alpha=1}^r \int_t^T \partial \theta[0]_\alpha(u) \partial \theta[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]
\[\quad + \left(\frac{\delta}{1-\delta}\right) \left\{ \sum_{\alpha=1}^r \int_t^T \partial \theta[0]_\alpha(u) Y_{t,u} \left( \int_u^T \partial r[0](s) Y_{t,s} ds \right) Y_{t,u}^{-1} \partial_\epsilon V[0, \cdot; \alpha] du \right\} \partial_\epsilon V(x, 0)\]

3. 
\[
\left(\frac{\delta}{1-\delta}\right) \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0) \left\{ \int_t^T \partial r[0](u) \dot{D}_1(t; u) du \right\}
\]

4. 
\[
\left(\frac{\delta}{1-\delta}\right) \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) \dot{D}_1(t; u) du \right\} \left\{ \int_t^T \partial r[0](u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]

5. 
\[
\left(\frac{\delta}{1-\delta}\right)^2 \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) \dot{D}_1(t; u) du \right\} \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial \theta[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]
\[\quad + \left(\frac{\delta}{1-\delta}\right) \sum_{\alpha=1}^r \left\{ \int_t^T \left( \sum_{\alpha'=1}^r \int_u^T \theta[0]_\alpha(s) \partial \theta[0]_{\alpha'}(s) ds \right) Y_{t,u}^{-1} \partial_\epsilon V[0, \cdot; \alpha] \partial \theta[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)\]

6. 
\[
\left(\frac{\delta}{1-\delta}\right) \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0) \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial \theta[0]_\alpha(u) \dot{D}_1(t; u) du \right\}
\]

7. 
\[
\left(\frac{\delta}{1-\delta}\right)^2 \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) \dot{D}_1(t; u) du \right\} \left\{ \int_t^T \partial r[0](u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]

8. 
\[
\left(\frac{\delta}{1-\delta}\right)^2 \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) \dot{D}_1(t; u) du \right\} \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial \theta[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]

9. 
\[
\left(\frac{\delta}{1-\delta}\right)^3 \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial r[0]_\alpha(u) \dot{D}_1(t; u) du \right\} \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \partial \theta[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]
\[\quad + \left(\frac{\delta}{1-\delta}\right) \left\{ \sum_{\alpha=1}^r \int_t^T \theta[0]_\alpha(u) \dot{D}_1(t; u) \partial \theta[0]_\alpha(u) Y_{t,u} du \right\} \partial_\epsilon V(x, 0)
\]
\[\quad + \left(\frac{\delta}{1-\delta}\right)^2 \left\{ \sum_{\alpha=1}^r \int_t^T \left( \sum_{\alpha'=1}^r \int_u^T \theta[0]_{\alpha'}(s) \partial \theta[0]_\alpha(s) ds \right) Y_{t,u}^{-1} \partial_\epsilon V[0, \cdot; \alpha] du \right\} \partial_\epsilon V(x, 0)\]
10. 
\[ \sum_{\alpha=1}^{r} \left( \int_{t}^{T} (\partial \theta_{\alpha}^{[0]}(u))^{2} \hat{D}_{1}(t; u)Y_{t,u}du \right) \partial_{t}V(x, 0) \]
\[ + \sum_{\alpha=1}^{r} \left( \int_{t}^{T} \theta_{\alpha}^{[0]}(u) \partial \theta_{\alpha}^{[0]}(u) \hat{D}_{1}(t; u)Y_{t,u}du + \int_{t}^{T} \theta_{\alpha}^{[0]}(u) \partial \theta_{\alpha}^{[0]}(u) \hat{Y}_{t,u}^{[1]}du \right) \partial_{x}V(x, 0) \]
\[ + \sum_{\alpha=1}^{r} \frac{1}{1 - \delta} \left( \int_{t}^{T} \theta_{\alpha}^{[0]}(u) \partial \theta_{\alpha}^{[0]}(u)Y_{t,u}du \right) \partial_{t}^{2}V(x, 0) \]
where
\[ \hat{Y}_{t,u}^{[1]} = \int_{t}^{u} Y_{t,u}^{-1} \{ \partial_{x}^{2}V_{0s}[\hat{D}_{1}(t; s)]Y_{t,s}ds + \partial_{t}Y_{0s}Y_{t,s}ds + \left( \frac{\delta}{1 - \delta} \right) \sum_{\alpha=1}^{r} \theta_{\alpha}(s) \partial_{x}V_{\alpha s}Y_{t,s}ds \} \]

11. 
\[ \left( \int_{t}^{T} \partial^{2}r_{\alpha}^{[0]}(u) \hat{D}_{1}(t; u)Y_{t,u}du + \int_{t}^{T} \partial r_{\alpha}^{[0]}(u) \hat{Y}_{t,u}^{[1]}du \right) \partial_{x}V(x, 0) \]
\[ + \left( \int_{t}^{T} \partial r_{\alpha}^{[0]}(u)Y_{t,u}du \right) \partial_{t}^{2}V(x, 0) \]

7.3 The Validity of the Asymptotic Expansions in Section 6

We start with the following more or less well known lemma.

**Lemma 10** Let \( \theta, \lambda \in \mathbb{R} - \{0\} \). Suppose that \((\xi_{t}^{\theta})_{t \in [0, T]}\) is a linear diffusion process satisfying the stochastic differential equation:

\[ d\xi_{t}^{\theta} = \theta \xi_{t}^{\theta} dt + dw_{t}, \quad \xi_{0}^{\theta} = x. \]

Let \( \alpha = (\theta^{2} - \lambda^{2})/2 \).

1. If \( x = 0 \) and if
\[
(\theta - \lambda) \left[ \frac{e^{2\lambda T} - 1}{2\lambda} \right] < 1,
\]
then
\[
\mathbb{E} \left[ \exp \left( \alpha \int_{0}^{T} (\xi_{t}^{\theta})^{2}dt \right) \right] = \exp \left( -\frac{\theta - \lambda}{2} T \right) \left( 1 - (\theta - \lambda) \left[ \frac{e^{2\lambda T} - 1}{2\lambda} \right] \right)^{-\frac{1}{2}}
\]
\[ = \exp \left( -\frac{\theta - \lambda}{2} T \right) \left[ \frac{2\lambda}{(\lambda - \theta)(e^{2\lambda T} - 1) + 2\lambda} \right]^{1/2}. \]

2. Let \( x \) be arbitrary.

(2 - i) If \( \theta < 0 \), then for any \( \lambda \in (\theta, -\theta) \),
\[
\mathbb{E} \left[ \exp \left( \alpha \int_{0}^{T} (\xi_{t}^{\theta})^{2}dt \right) \right] \leq \exp \left( \frac{\lambda - \theta}{2} (x^{2} + T) \right).
\]
If $\theta > 0$, then for any $\lambda \in (-\theta, \theta)$, and if 

$$
(\theta - \lambda) \left[ \frac{e^{2\lambda T} - 1}{2\lambda} \right] < \frac{1}{2},
$$

(53)

$$
E \left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] \leq \exp \left( \frac{\theta - \lambda}{2} (x^2 + T) + (\theta - \lambda)(xe^{\lambda T})^2 \right) \cdot \left[ \frac{\lambda}{(\lambda - \theta)(e^{2\lambda T} - 1) + \lambda} \right]^{1/2}.
$$

Proof. Let $\theta, \lambda \in \mathbb{R}$ (any real numbers). Denote by $\mu_{\xi^\theta}$ and $\mu_{\xi^\lambda}$ the measures corresponding to the processes $\xi_t^\theta$ and $\xi_t^\lambda$:

$$
d\xi_t^\theta = \theta \xi_t^\theta dt + dw_t, \quad \xi_0^\theta = x
$$

$$
d\xi_t^\lambda = \lambda \xi_t^\lambda dt + dw_t, \quad \xi_0^\lambda = x
$$

the measures $\mu_{\xi^\theta}$ and $\mu_{\xi^\lambda}$ are equivalent and

$$
\frac{d\mu_{\xi^\theta}}{d\mu_{\xi^\lambda}}(\xi_t^\lambda) = \exp \left\{ (\theta - \lambda) \int_0^T \xi_t^\lambda d\xi_t^\lambda - \frac{\theta^2 - \lambda^2}{2} \int_0^T (\xi_t^\lambda)^2 dt \right\}.
$$

Put $C = C([0, T])$. Then

$$
E \left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] = \int_C \exp \left( \alpha \int_0^T (x_t^\theta)^2 dt \right) \mu_{\xi^\theta}(dx) = \int_C \exp \left( \alpha \int_0^T (x_t^\theta)^2 dt \right) \frac{d\mu_{\xi^\theta}}{d\mu_{\xi^\lambda}}(x) \mu_{\xi^\lambda}(dx) = E \left[ \exp \left( \alpha \int_0^T (\xi_t^\lambda)^2 dt \right) \right] \exp \left\{ (\theta - \lambda) \int_0^T \xi_t^\lambda d\xi_t^\lambda - \frac{\theta^2 - \lambda^2}{2} \int_0^T (\xi_t^\lambda)^2 dt \right\}.
$$

Let us take

$$
\alpha = \frac{\theta^2 - \lambda^2}{2}.
$$

(54)

(In particular, if $\alpha \geq 0$, then $|\theta| \geq |\lambda|$.) Then

$$
E \left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] = E \left[ \exp \left\{ (\theta - \lambda) \int_0^T \xi_t^\lambda d\xi_t^\lambda \right\} \right].
$$

Using Itô’s formula

$$
(\xi_t^\lambda)^2 = (\xi_0^\lambda)^2 + 2 \int_0^T \xi_t^\lambda d\xi_t^\lambda + T,
$$

31
we after all obtain
\[
E\left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] = \exp \left( -\frac{\theta - \lambda}{2} (x^2 + T) \right) 
\cdot E\left[ \exp \left\{ \frac{\theta - \lambda}{2} (\xi_T^\lambda)^2 \right\} \right] \tag{55}
\]

Noting that\(^2\) \(\xi_T^\lambda\) is Gaussian:
\[
\xi_T^\lambda \sim N \left( xe^{\lambda T}, \frac{e^{2\lambda T} - 1}{2\lambda} \right).
\]

(1) The case \(x = 0\). We have
\[
(\xi_T^\lambda)^2 \left[ \frac{e^{2\lambda T} - 1}{2\lambda} \right]^{-1} \sim \chi_1^2,
\]
where \(\chi_1^2\) is the chi-square distribution of degree one. It is known that
\[
E[\exp(\lambda t^2)] = (1 - 2t)^{-\frac{1}{2}} \quad (t < \frac{1}{2}).
\]
Thus, if
\[
\frac{\theta - \lambda}{2} \left[ \frac{e^{2\lambda T} - 1}{2\lambda} \right] < \frac{1}{2}, \tag{56}
\]
\[
E\left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] = \exp \left( -\frac{\theta - \lambda}{2} T \right) \left( 1 - 2 \frac{\theta - \lambda}{2} \left[ \frac{e^{2\lambda T} - 1}{2\lambda} \right] \right)^{-\frac{1}{2}}
\]
\[
= \exp \left( -\frac{\theta - \lambda}{2} T \right) \left[ \frac{2\lambda}{(\lambda - \theta)(e^{2\lambda T} - 1) + 2\lambda} \right]^{1/2},
\]
where \(\alpha, \theta\) and \(\lambda\) must satisfy (54) and (56). The most simple case may be the one where \(\lambda = 0, \alpha = \theta^2/2\) for given \(\theta < 0\). In that case, (56) becomes \(\theta T < 1\), which is automatically satisfied for \(\theta < 0\).

(2) The case arbitrary \(x \in \mathbb{R}\). \(^3\)
(2-i) \(\theta < 0\): It follows from (55) that
\[
E\left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] \leq \exp \left( \frac{\lambda - \theta}{2} (x^2 + T) \right)
\]
for \(\lambda \in (\theta, -\theta)\).
(2-ii) \(\theta > 0\): From (55), we have
\[
E\left[ \exp \left( \alpha \int_0^T (\xi_t^\theta)^2 dt \right) \right] \leq \exp \left( -\frac{\theta - \lambda}{2} (x^2 + T) + (\theta - \lambda)(xe^{\lambda T})^2 \right)
\]
\[
\cdot E\left[ \exp \left\{ (\theta - \lambda)(\xi_T^\lambda - xe^{\lambda T})^2 \right\} \right]
\]
\(^2\) \(\lambda\) may still be positive or negative. If \(\lambda = 0\), then the variance is \(T\).
\(^3\) When \(x \neq 0\), \(\xi_T^\lambda\) has the non-central \(\chi^2\) distribution with degree one. It is possible to express the moment generating function, but it is not clever for the present purpose.
for $\lambda \in (-\theta, \theta)$. Moreover, if (53) then
\[
E \left[ \exp \left( \alpha \int_0^T (\xi_t^2) dt \right) \right] \leq \exp \left( -\frac{\theta - \lambda}{2} (x^2 + T) + (\theta - \lambda)(xe^{\lambda T})^2 \right) \\
\quad \quad \cdot \left( 1 - 2(\theta - \lambda) \left[ e^{2\lambda T} - 1 \right] \right)^{-\frac{1}{2}} \\
= \exp \left( -\frac{\theta - \lambda}{2} (x^2 + T) + (\theta - \lambda)(xe^{\lambda T})^2 \right) \\
\quad \quad \cdot \left( \frac{\lambda}{(\lambda - \theta)(e^{2\lambda T} - 1) + \lambda} \right)^{1/2}.
\]

Let us return to the example in Section 6 and verify the uniform $L^p$ integrability of $\zeta_{t,T}$. Since $r_u^\epsilon$ is bounded, it suffices for the validity of the asymptotic expansion (See the last paragraph of Section 4.) to show that the uniform (in $\epsilon$) $L^p$-integrability of the functional
\[
Z = \exp \left( a \int_0^T X_u^{\epsilon(2)} dw_u + b \int_0^T (X_u^{\epsilon(2)})^2 du \right),
\]
where $a, b$ are constants. Let $p, q \in (1, \infty)$ and let $q' = q/(q - 1)$. Taking $c = q(ap)^2/2$ and using Hölder’s inequality, we see that
\[
E[Z^p] \leq E \left[ \exp \left( qap \int_0^T X_u^{\epsilon(2)} dw_u - qc \int_0^T (X_u^{\epsilon(2)})^2 du \right) \right]^{1/q} \\
\quad \quad \cdot E \left[ \exp \left( q'(c + bp) \int_0^T (X_u^{\epsilon(2)})^2 du \right) \right]^{1/q'}.
\]
Since $qc = (qap)^2/2$, the first factor on the right-hand side is not larger than one, hence it is sufficient to show that for any $L > 0$, there exists a constant $\epsilon(L) > 0$ such that
\[
\sup_{\epsilon \in (0, \epsilon(L))]} E \left[ \exp \left( L \int_0^T (X_u^{\epsilon(2)})^2 du \right) \right] < \infty. \quad (57)
\]

If we put $x_t = (\epsilon \sigma_2)^{-1}(X_t^{\epsilon(2)} - \bar{X}(2))$, then $(x_t)$ satisfies the stochastic differential equation
\[
dx_t = -\kappa_2 x_t dt + dw_t, \\
x_0 = \epsilon^{-1} c_0,
\]
where $c_0 = (\sigma_2)^{-1}(X_0^{\epsilon(2)} - \bar{X}(2))$. Therefore, in order to obtain (57), it suffices to show that for any $L > 0$, there exists a constant $\epsilon(L) > 0$ such that
\[
\sup_{\epsilon \in (0, \epsilon(L))]} E \left[ \exp \left( Le^2 \int_0^T (x_u)^2 du \right) \right] < \infty. \quad (58)
\]
Here $x_u$ depends on $\epsilon$. Applying Lemma 10 (2-i) to the case that $\theta = -\kappa_2$, $x = c_0 \epsilon^{-1}$ and $\lambda = -(\kappa^2 - 2Le^2)^{1/2}$, we obtain (58).
<table>
<thead>
<tr>
<th>T (Investment horizon)</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total demand</td>
<td>25.31</td>
<td>26.41</td>
<td>27.80</td>
<td>29.26</td>
<td>30.70</td>
</tr>
<tr>
<td>Mean variance</td>
<td>25.00</td>
<td>25.00</td>
<td>25.00</td>
<td>25.00</td>
<td>25.00</td>
</tr>
<tr>
<td>IR-hedge</td>
<td>2.14</td>
<td>4.11</td>
<td>5.92</td>
<td>7.59</td>
<td>9.13</td>
</tr>
<tr>
<td>MPR-hedge</td>
<td>-1.83</td>
<td>-2.70</td>
<td>-3.12</td>
<td>-3.33</td>
<td>-3.43</td>
</tr>
</tbody>
</table>

Table 1: Asymptotic Expansion(%, $R = 2.0$)

<table>
<thead>
<tr>
<th>R ($1 - \delta$)</th>
<th>0.5</th>
<th>1</th>
<th>1.5</th>
<th>4</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total demand</td>
<td>110.37</td>
<td>50</td>
<td>33.13</td>
<td>14.34</td>
<td>12.25</td>
</tr>
<tr>
<td>Mean variance</td>
<td>100.00</td>
<td>50</td>
<td>33.33</td>
<td>12.50</td>
<td>10.00</td>
</tr>
<tr>
<td>IR-hedge</td>
<td>-4.28</td>
<td>0</td>
<td>1.43</td>
<td>3.21</td>
<td>3.42</td>
</tr>
<tr>
<td>MPR-hedge</td>
<td>14.65</td>
<td>0</td>
<td>-1.63</td>
<td>-1.37</td>
<td>-1.17</td>
</tr>
</tbody>
</table>

Table 2: Asymptotic Expansion(%, $T = 1.0$)

<table>
<thead>
<tr>
<th>T (Investment horizon)</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total demand</td>
<td>25.37</td>
<td>26.49</td>
<td>27.79</td>
<td>29.10</td>
<td>30.41</td>
</tr>
<tr>
<td>Mean variance</td>
<td>25.00</td>
<td>25.00</td>
<td>25.00</td>
<td>25.00</td>
<td>25.00</td>
</tr>
<tr>
<td>IR-hedge</td>
<td>2.14</td>
<td>4.12</td>
<td>5.95</td>
<td>7.63</td>
<td>9.19</td>
</tr>
<tr>
<td>MPR-hedge</td>
<td>-1.77</td>
<td>-2.63</td>
<td>-3.16</td>
<td>-3.53</td>
<td>-3.78</td>
</tr>
</tbody>
</table>

Table 3: Monte Carlo Simulation(%, $R = 2.0$)

<table>
<thead>
<tr>
<th>R ($1 - \delta$)</th>
<th>0.5</th>
<th>1</th>
<th>1.5</th>
<th>4</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total demand</td>
<td>113.07</td>
<td>50</td>
<td>33.18</td>
<td>14.35</td>
<td>12.22</td>
</tr>
<tr>
<td>Mean variance</td>
<td>100.00</td>
<td>50</td>
<td>33.33</td>
<td>12.50</td>
<td>10.00</td>
</tr>
<tr>
<td>IR-hedge</td>
<td>-4.26</td>
<td>0</td>
<td>1.43</td>
<td>3.22</td>
<td>3.43</td>
</tr>
<tr>
<td>MPR-hedge</td>
<td>17.33</td>
<td>0</td>
<td>-1.58</td>
<td>-1.37</td>
<td>-1.22</td>
</tr>
</tbody>
</table>

Table 4: Monte Carlo Simulation(%, $T = 1.0$)